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A NOTE ON ALMOST s -CONTINUITY

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Abstract. T. Noiri, M. B. Ahmad and M. Khan introduced the notion of almost s -continuous functions [20] since then the function studied by various authors [1,4,11] Continuing in the spirit of this papers we obtain several properties and new characterizations of almost s -continuous functions. We improve and strengthen some of the known results. The concept of co - SR -closed graph is introduced.

1. INTRODUCTION AND PRELIMINARIES

Almost s -continuous functions being both quasi-irresolute and almost continuous, introduced by T. Noiri, M. B. Ahmad and M. Khan [20]. In [4] Dontchev, Ganster and Reilly introduced quasi-open sets and they related ultra Hausdorffness and almost s -continuity. Note that ultra Hausdorffness implies totally disconnectedness [25]. So almost s -continuity can be considered as a tool for studying various disconnectedness properties. Almost s -continuity generate clopen sets from semi-regular sets under the inverse image so this function equivalent to γ -continuity introduced by Ganguly and Basu [9] in 1992.

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Quasi-open sets can be used for characterizing almost s -continuity. Since every clopen set is quasi-open this improves some of the almost s -continuity characterizations. In [1] Cho, studied net characterizations of almost s -continuity, we strengthened and extended his results using clopen sets. In the same manner using co - SR -closed graphs instead of almost s -closed graphs some results of Jafari and Noiri [11] are improved. In addition using almost s -continuity and co - SR -closed graphs, ultra Hausdorff spaces are characterized.

Throughout this paper (X, τ) and (Y, σ) (or simply X and Y) represent nonempty topological spaces on which no separation axioms are assumed, unless otherwise mentioned. For a subset S of (X, τ) , $cl(S)$ and $int(S)$ represent the closure of S and the interior of S , respectively. A subset S of a space (X, τ) is said to be semi-open [16] if $S \subset cl(int(S))$. The family of all semi-open sets of X is denoted by $SO(X)$. The complement of a semi-open set is said to be semi-closed. The semiclosure of S , denoted by $scl(S)$, is the intersection of all semi-closed sets containing S . The family of all semi-closed sets of X is denoted by $SC(X)$. A subset S of a space (X, τ) is said to be semi-regular [14] if it is both semiopen as well as semi-closed. The family of all semi-regular sets of a space X and that containing a point x of X are respectively denoted by $SR(X)$ and $SR(X, x)$. A point $x \in X$ is said to be in the semi- θ -closure [14] of A , denoted by $scl_\theta(A)$, if $A \cap scl(V) \neq \emptyset$ for every $V \in SO(X, x)$. If $scl_\theta(A) = A$, then A is said to be semi- θ -closed. The complement of a semi- θ -closed set is said to be semi- θ -open.

The quasi-component [25] of a point $x \in X$ is the intersection of all clopen subsets of X which contain the point x . The quasi-topology τ_q on X is the topology having as base clopen subsets of (X, τ) . The closure of each point in quasi-topology is precisely the quasi-component of that point. The open (resp. closed) subsets of the quasi-topology is called quasi-open [4] (resp. quasi-closed [4]). For a space (X, τ) the space (X, τ_q) is called by Staum [25] the ultraregular kernel of X and denoted by X_q for simplicity. A space (X, τ) is called ultraregular [25] if $\tau = \tau_q$. For a subset A of a space X , we define the quasi-interior (resp. quasi-closure) of A , denoted by $int_q(A)$ (resp. $cl_q(A)$), defined by $int_q(A) = \cup\{U \text{ is quasi-open: } U \subset A\}$, (resp. $cl_q(A) = \cap\{F \text{ is quasi-closed: } A \subset F\}$).

Lemma 1. [9] *Let A be a subset of a space X .*

- (a): If $A \in SO(X)$ then $scl(A) \in SR(X)$ and $scl(A) = scl_\theta(A)$;
- (b): If $A \in SR(X)$ then $X - A \in SR(X)$;

Lemma 2. [6,14,20] Let A be a subset of a space X , the following statements are equivalent:

- (a): $A \in SR(X)$;
- (b): $A = scl(sint(A))$;
- (c): $A = sint(scl(A))$;
- (d): A is semi- θ -closed and semi- θ -open.

Definition 3. A function $f : X \rightarrow Y$ is said to be almost s -continuous [20] if for each point $x \in X$ and each $V \in SO(Y, f(x))$, there exists an open set U of X containing x such that $f(U) \subset scl(V)$.

2. CHARACTERIZATIONS

Definition 4. A subfamily m_X of the power set $\wp(X)$ of a nonempty set X is called a minimal structure [24] (briefly m -structure) on X if $\emptyset \in m_X$ and $X \in m_X$. By (X, m_X) , we denote a nonempty subset X with a minimal structure m_X on X . Each member of m_X is said to be m_X -open and the complement of m_X -open set is said to be m_X -closed. For a subset A of X , the m_X -closure of A and the m_X -interior of A are defined in [18] as $m_X\text{-Cl}(V) = \cap\{F : A \subset F, X - F \in m_X\}$ and $m_X\text{-Int}(V) = \cup\{U : U \subset A, U \in m_X\}$.

Remark 5. Let (X, τ) be a topological space. Then the families $\tau, \tau_q, SO(X), PO(X), \alpha(X), \beta(X) (= \beta O(X)), SR(X), \beta R(X)$ are all m -structures on X .

Definition 6. A function $f : (X, m_X) \rightarrow (Y, m_Y)$, where X and Y are nonempty sets with minimal structures m_X and m_Y , respectively, is said to be weakly M -continuous [22] (M -continuous [24]) at $x \in X$ if for each $V \in m_Y$ containing $f(x)$ such that $f(U) \subset m_X\text{-Cl}(V)$ (resp. $f(U) \subset V$). A function $f : (X, m_X) \rightarrow (Y, m_Y)$ is said to be weakly M -continuous (resp. M -continuous) if it has the property at each point $x \in X$.

Theorem 7. For a function $f : X \rightarrow Y$, the following are equivalent:

- (a): f is almost s -continuous.
- (b): For each $x \in X$ and each $V \in SR(Y, f(x))$, there exists a clopen set U containing x such that $f(U) \subset V$;

- (c): For each $x \in X$ and each $V \in SR(Y, f(x))$, there exists an quasi-open set U of X containing x such that $f(U) \subset V$;
 (d): $f : (X, \tau_q) \rightarrow (Y, SO(Y))$ is weakly M -continuous.
 (e): $f^{-1}(V) \subset \text{int}_q(f^{-1}(scl(V)))$ for every $V \in SO(Y)$;
 (f): $cl_q(f^{-1}(sint(F))) \subset f^{-1}(F)$ for every $F \in SC(Y)$;
 (g): $cl_q(f^{-1}(V)) \subset f^{-1}(scl(V))$ for every $V \in SO(Y)$.
 (h): $f(cl_q(A)) \subset scl_\theta(f(A))$ for each subset A of X .
 (i): $cl_q(f^{-1}(B)) \subset f^{-1}(scl_\theta(B))$ for each subset B of Y .

Proof. (a) \Rightarrow (b): This is known by Theorem 3.3 of [20].

(b) \Rightarrow (c) \Rightarrow (a): These implications are clear from the definition of quasi topology.

(c) \Rightarrow (d) Let $x \in X$ and $V \in SR(Y, f(x))$. Then by (c) there exists a quasi-open set U containing x such that $f(U) \subset V$. Since every semi-regular set is semi-open, f is M -continuous, hence weakly M -continuous.

(d) \Rightarrow (a) Let $x \in X$ and $V \in SO(Y, f(x))$ then there exists a quasi-open set U containing x such that $f(U) \subset scl(V)$. Since U is quasi open there exists an open set W in U containing x such that $f(W) \subset scl(V)$ and by Definition 3 f is almost s -continuous.

(c) \Rightarrow (e): Let $V \in SO(Y)$ and $x \in f^{-1}(V)$. Then $f(x) \in V$ and $scl(V) \in SR(Y, f(x))$ hence by (c), there exists a quasi-open set U of X containing x such that $f(U) \subset scl(V)$. Then $x \in U \subset f^{-1}(scl(V))$ and hence $x \in \text{int}_q(f^{-1}(scl(V)))$.

(e) \Leftrightarrow (a): It follows from Theorem 3.2 of [22].

(f) \Rightarrow (g): Let $F \in SC(Y)$, then $Y - F \in SO(Y)$ and by (e), we have $f^{-1}(Y - F) \subset \text{int}_q(f^{-1}(scl(Y - F)))$ i.e., $X - f^{-1}(F) \subset \text{int}_q(f^{-1}(scl(Y - F))) = \text{int}_q(f^{-1}(Y - sint(F))) = X - cl_q(f^{-1}(sint(F)))$ Hence we obtain $cl_q(f^{-1}(sint(F))) \subset f^{-1}(F)$.

(f) \Leftrightarrow (a): It follows from Theorem 2.1 of [23].

(f) \Rightarrow (g): Let $V \in SO(Y)$. Then $scl(V)$ is semi-closed, by (e) $cl_q(f^{-1}(V)) \subset cl_q(f^{-1}(scl(V))) = cl_q(f^{-1}(sint(scl(V)))) \subset f^{-1}(scl(V))$.

(g) \Leftrightarrow (a) It follows from Theorem 3.4 of [22].

(a) \Rightarrow (h) \Rightarrow (i) \Rightarrow (a): It follows from Theorem 3.3 of [22]. \square

Definition 8. A filter base \mathcal{F} is said to be;

- (a): s - θ -convergent [1] to a point x in X , if for any semi-open set U containing x there exist $B \in \mathcal{F}$ such that $B \subset scl(U)$;

(b): *clopen convergent to a point x in X , if for any clopen set U containing x , there exist $B \in \mathcal{F}$ such that $B \subset U$.*

Theorem 9. *A function $f : X \rightarrow Y$ is almost s -continuous if and only if for each point $x \in X$ and each filter base \mathcal{F} in X clopen converging to x the filter base $f(\mathcal{F})$ is s - θ -convergent to $f(x)$.*

Proof. Suppose that $x \in X$ and \mathcal{F} is any filter base in X clopen converges to x . Since f is almost s -continuous for any semi-open set V containing $f(x)$ $scl(V) \in SR(Y, f(x))$ and by Theorem 7, there exists a clopen set U containing x in X such that $f(U) \subset scl(V)$. Since \mathcal{F} is clopen convergent to x in X then there exists $B \in \mathcal{F}$ such that $B \subset U$. It follows that $f(B) \subset scl(V)$. This means that $f(\mathcal{F})$ is s - θ -convergent to $f(x)$.

Conversely, let x be a point in X and V be a semi-open set containing $f(x)$. If we set $\mathcal{F} = \{U : U \text{ is clopen and } x \in U\}$, then \mathcal{F} will be a filter base which clopen converges to x . So there exists $U \in \mathcal{F}$ such that $f(U) \subset scl(V)$. This completes the proof. \square

Definition 10. *A net (x_i) in a space X , θ -converges (resp. clopen converges [10], s - θ -converges [1]) to x if and only if for each open (resp. clopen, semi-open,) set U containing x , there exists i_0 such that $x_i \in cl(U)$ (resp. $x_i \in U$, $x_i \in scl(U)$) for all $i \geq i_0$.*

Lemma 11. *For a net (x_i) in a space X ;*

- (a):** [1] if (x_i) s - θ -converges to x , then (x_i) θ -converges to x ;
- (b):** [2] if (x_i) converges to x , then (x_i) θ -converges to x ;
- (c):** [10] if (x_i) converges or θ -converges to x , then (x_i) clopen converges to x .

Theorem 12. *For a function $f : X \rightarrow Y$, the following statements are equivalent:*

- (a):** f is almost s -continuous;
- (b):** For each $x \in X$ and each net (x_i) in X which clopen converges to x , the net $(f(x_i))$ s - θ -converges to $f(x)$;
- (c):** For each $x \in X$ and each net (x_i) in X which θ -converges to x , the net $(f(x_i))$ s - θ -converges to $f(x)$;
- (d):** For each $x \in X$ and each net (x_i) in X which converges to x , the net $(f(x_i))$ s - θ -converges to $f(x)$.

Proof. (a) \Rightarrow (b) Let $x \in X$ and let (x_i) be a net in X such that (x_i) clopen converges to x . Let V be a semi-open set containing $f(x)$. Since f is almost s -continuous and $scl(V) \in SR(Y)$, there exists a clopen set U containing x such that $f(U) \subset scl(V)$. Since (x_i) clopen converges to x , there exists i_0 such that $x_i \in U$ for all $i \geq i_0$. Hence $f(x_i) \in scl(V)$ for all $i \geq i_0$.

(b) \Rightarrow (a) Suppose that f is not *almost s -continuous*. Then there exists $x \in X$ and $V \in SO(Y, f(x))$ such that $f(U) \not\subseteq scl(V)$ for all clopen neighborhood U of x . Thus for every clopen neighborhood U of x we can find $x_U \in U$ such that $f(x_U) \notin scl(V)$. Let $\mathcal{N}(x)$ be the set of clopen neighborhoods of x in X . The set $\mathcal{N}(x)$ with the relation of inverse inclusion (that is $U_1 \leq U_2$ if and only if $U_2 \subseteq U_1$) form a directed set (Theorem 1.1 of [10]). Clearly the net $\{x_U : U \in \mathcal{N}(x)\}$ clopen converges to x in X but $(f(x_U))_{U \in \mathcal{N}(x)}$ does not s - θ -converge to $f(x)$.

(b) \Rightarrow (c) Let $x \in X$ and let (x_i) be a net in X such that (x_i) θ -converges to x . By Lemma 11 (x_i) clopen converges to x . By (b), $(f(x_i))$ s - θ -converges to $f(x)$.

For the proof of the other implications see [1]. □

By Lemma 11 and Theorem 12 we have the following as corollary. This is an improvement of Corollary 3.1 of [1].

Corollary 13. *If a function $f : X \rightarrow Y$ is almost s -continuous then, for each $x \in X$ and each net (x_i) in X which clopen converges to x , the net $(f(x_i))$ θ -converges to $f(x)$.*

Proposition 14. [1] *A net (x_i) in a space X , s - θ -converges to x if and only if for each semiregular set U containing x , there exists i_0 such that $x_i \in U$ for all $i \geq i_0$.*

By Theorem 12 and Proposition 14 we have the following extension of Corollary 3.2 of [1].

Theorem 15. *For a function $f : X \rightarrow Y$, the following are equivalent:*

- (a): *f is almost s -continuous;*
- (b): *If for each $x \in X$ and, a net (x_i) in X clopen converges to x then for each $V \in SR(Y, f(x))$, there exists i_0 such that $f(x_i) \in V$ for all $i \geq i_0$;*

- (c): If for each $x \in X$ and, a net (x_i) in X θ -converges to x then for each $V \in SR(Y, f(x))$, there exists i_0 such that $f(x_i) \in V$ for all $i \geq i_0$;
- (d): If for each $x \in X$ and, a net (x_i) in X converges to x then for each $V \in SR(Y, f(x))$, there exists i_0 such that $f(x_i) \in V$ for all $i \geq i_0$.

3. SEPARATION AXIOMS AND co - SR -CLOSED GRAPHS

Definition 16. A space X is said to be

- (a): ultra Hausdorff [25] if every two distinct points of X can be separated by disjoint clopen sets.
- (b): semi- T_2 [17] if for each pair of distinct points x and y in X , there exist semi-open sets U and V of X containing x and y , respectively, such that $U \cap V = \emptyset$ (or equivalently $scl(U) \cap scl(V) = \emptyset$ [14]).
- (c): clopen T_1 [8] (\equiv ultra T_1 [13]) if for each pair of distinct points x and y of X , there exist clopen sets U and V containing x and y respectively such that $y \notin U$ and $x \notin V$.
- (d): ultra T_0 [13] if for each pair of distinct points x and y of X , there exist a clopen set U containing one of the points x and y but not the other.

Remark 17. Kohli and Singh proved that [13] ultra Hausdorff, clopen T_1 , and ultra T_0 axioms are all equivalent.

Definition 18. [22] A nonempty set X is with a minimal structure m_X , (X, m_X) , is said to be m -Hausdorff if for each distinct points $x, y \in X$, there exist $U, V \in m_X$ containing x and y , respectively, such that $U \cap V = \emptyset$.

Theorem 19. [26] If $f : (X, \tau_q) \rightarrow (Y, m_Y)$ is a weakly M -continuous function and (Y, m_Y) is m -Hausdorff, then f has quasi-closed point inverses in X .

Corollary 20. If $f : (X, \tau) \rightarrow (Y, \sigma)$ is almost s -continuous and (Y, σ) is semi- T_2 then f has quasi-closed point inverses in X .

Recall that for a function $f : X \rightarrow Y$, the subset $\{(x, f(x)) : x \in X\} \subset X \times Y$ is called the graph of f and is denoted by $G(f)$.

Definition 21. A function $f : (X, m_X) \rightarrow (Y, m_Y)$ is said to have a strongly M -closed graph [22] if and only if for each $(x, y) \in (X \times Y) - G(f)$ there exists an m_X -open set U containing x and an m_Y -open set V containing y such that $(U \times m_Y\text{-Cl}(V)) \cap G(f) = \emptyset$.

Lemma 22. [22] A function $f : (X, m_X) \rightarrow (Y, m_Y)$ has a strongly M -closed graph if and only if for each $(x, y) \in (X \times Y) - G(f)$ there exists an m_X -open set U containing x and m_Y -open set V containing y such that $f(U) \cap m_Y\text{-Cl}(V) = \emptyset$.

Definition 23. A graph $G(f)$ of a function $f : X \rightarrow Y$ is said to be co-SR-closed if for each $(x, y) \in (X \times Y) - G(f)$, there exists a clopen set U in X containing x and $V \in SR(Y, y)$ such that $(U \times V) \cap G(f) = \emptyset$.

Remark 24. If a function $f : (X, m_X) \rightarrow (Y, m_Y)$ has the strongly M -closed graph, then for the special case $m_X = \tau_q$ and $m_Y = SO(Y)$, $G(f)$ has co-SR-closed graph and we may state the following.

Theorem 25. The following properties are equivalent for a graph $G(f)$ of a function:

- (a): $G(f)$ is co-SR-closed.
- (b): for each $(x, y) \in (X \times Y) - G(f)$, there exists a clopen set U containing x in X and $V \in SR(Y, y)$ such that $f(U) \cap V = \emptyset$.
- (c): for each point $(x, y) \in (X \times Y) - G(f)$, there exists a clopen set U containing x in X and $V \in SO(Y, y)$ such that $f(U) \cap scl(V) = \emptyset$.
- (d): for each point $(x, y) \in (X \times Y) - G(f)$, there exists a quasi-open set U containing x in X and $V \in SO(Y, y)$ such that $f(U) \cap scl(V) = \emptyset$.

Theorem 26. If $f : X \rightarrow Y$ is almost s -continuous function and Y is semi- T_2 , then $G(f)$ is co-SR-closed in $X \times Y$.

Proof. First suppose Y is semi- T_2 . Let $(x, y) \in (X \times Y) - G(f)$. It follows that $f(x) \neq y$. Since Y is semi- T_2 , there exist $V \in SO(Y, f(x))$ and $W \in SO(Y, y)$ such that $scl(V) \cap scl(W) = \emptyset$. Since f is almost s -continuous, there exists a clopen set $U = f^{-1}(scl(V))$ in X containing x such that $f(U) \subset scl(V)$. Therefore $f(U) \cap scl(W) = \emptyset$ and $G(f)$ is co-SR-closed with respect to $X \times Y$. \square

Theorem 27. Let $f : X \rightarrow Y$ have a co-SR-closed graph then the following properties hold:

- (a): if f is injective then X is ultra Hausdorff;
- (b): if f is surjective then X is semi- T_2 .

Proof. (a) Suppose that x and y are any two distinct points of X by the injectivity of f , $(x, f(y)) \notin G(f)$. Since $G(f)$ is co - SR -closed, by Theorem 25, there exist a clopen set U containing x and $V \in SO(Y, f(y))$ such that $f(U) \cap scl(V) = \emptyset$. We have $U \cap f^{-1}(scl(V)) = \emptyset$. Therefore $y \notin U$. Then U and $X - U$ are disjoint clopen sets containing x and y , respectively. Hence X is ultra Hausdorff.

(b) Let y_1 and y_2 be any two distinct points of Y . Since f is surjective there exists a point $x \in X$ such that $f(x) = y_2$. Since $G(f)$ is co - SR -closed and $(x, y_1) \notin G(f)$ there exists a clopen set U containing x and $V \in SR(Y, y_1)$ such that $f(U) \cap V = \emptyset$. Therefore we have $y_2 \in f(U) \subset Y - V \in SR(Y)$ and hence Y is semi- T_2 . \square

Note that since *ultra Hausdorff spaces are totally disconnected* [25] first part of the theorem characterizes totally disconnectednes.

Definition 28. A subset K of a nonempty set X with a minimal structure m_X is said to be m -compact [21] (m -closed [21]) relative to (X, m_X) if any cover $\{U_i : i \in I\}$ of K by m_X -open sets, there exists a finite subset I_0 of I such that $K \subseteq \cup\{U_i : i \in I_0\}$ ($K \subseteq \cup\{m_X - Cl(U_i) : i \in I_0\}$). (X, m_X) is m -closed if X is m -closed relative to (X, m_X) .

Definition 29. A subset K of a space X is said to be s -closed [14] relative to X if for every cover $\{V_\alpha : \alpha \in I\}$ of K by semi-open sets of X , there exists a finite subset I_0 of I such that $K \subset \cup\{scl(V_\alpha) : \alpha \in I_0\}$.

Theorem 30. [19] Let $f : (X, m_X) \rightarrow (Y, m_Y)$ be a function. Assume that m_X is a base for a topology. If the graph $G(f)$ is strongly M -closed, then $m_X - Cl(f^{-1}(K)) = f^{-1}(K)$ whenever the set $K \subseteq Y$ is m -closed relative to (Y, m_Y) .

Corollary 31. [26] If a function $f : (X, \tau_q) \rightarrow (Y, m_Y)$ has a strongly M -closed graph, then $f^{-1}(K)$ is quasi-closed in (X, τ_q) for each set K which is m -closed relative to (Y, m_Y) .

Corollary 32. If a function $f : X \rightarrow Y$ has co - SR -closed graph, then $f^{-1}(K)$ is quasi-closed in X for every subset K which is s -closed relative to Y .

Theorem 33. *If a function $f : X \rightarrow Y$ has a co-SR-closed graph and Y is s -closed then f is almost s -continuous.*

Proof. Let $V \in SR(Y)$, then by Lemma 1, $Y - V \in SR(Y)$. By the s -closedness of Y it follows from Theorem 1 of [15], $Y - V$ is s -closed. By Corollary 32, $f^{-1}(Y - V) = X - f^{-1}(V)$ is quasi-closed, hence $f^{-1}(V)$ is quasi open. Set $U = f^{-1}(V)$, then $f(U) \subset V$, and by Theorem 7, f is almost s -continuous. \square

Corollary 34. *Let Y be an s -closed semi- T_2 space. The following are equivalent for a function $f : X \rightarrow Y$:*

- (a): f is almost s -continuous;
- (b): $G(f)$ is co-SR-closed;
- (c): for each K , s -closed relative to Y , $f^{-1}(K)$ is quasi-closed in X .

Proof. This is a direct consequence of Theorems 26, 33 and Corollary 32. \square

Definition 35. *A topological space (X, τ) is called countably rs -compact [5] (resp. countably S -closed [3], mildly countably compact [25]) if every countable cover of X by semi-regular (resp. regular closed, clopen) sets has a finite subcover.*

Definition 36. *A topological space (X, τ) is called rs -Lindelöf [7] (resp. rc -Lindelöf [12]) if every cover of X by semi-regular (resp. regular closed) sets has a countable subcover.*

Definition 37. *For any infinite cardinal κ , a topological space (X, τ) is called κ -extremally disconnected [5] (κ -e.d.) if the boundary of every regular open set has cardinality (strictly) less than κ .*

Theorem 38. *Let $f : (X, \tau) \rightarrow (Y, \sigma)$ be an almost s -continuous surjection, then the following properties hold:*

- (a): *If X is mildly countably compact, then Y is countably S -closed and \aleph_0 -e.d. (almost extremally disconnected).*
- (b): *If X is mildly Lindelöf, then Y is rc -Lindelöf and ω_1 -e.d. (the boundary of every regular open set is at most countable).*

Proof. (a) Let $f : (X, \tau) \rightarrow (Y, \sigma)$ be an almost s -continuous surjection. If X is mildly countably compact, then Y is countably rs -compact by Theorem 2.6 of [4]. Then Y is both countably S -closed and \aleph_0 -e.d. (almost extremally disconnected) by Theorem 3.13 of [5].

(b) Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be an almost s -continuous surjection. If X is mildly Lindelöf, then Y is rs -Lindelöf. by Theorem 2.6 of [4]. Then Y is rc -Lindelöf and ω_1 -e.d. by Theorem 3.14 of [5]. \square

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