

## APPLICATIONS OF WEAK-BISPLIT GRAPHS

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**Abstract.** In this paper, using weak-decomposition, we give necessary and sufficient conditions for a graph to be weak-bisplit cograph. We also give we give some applications in optimization problems.

### 1. INTRODUCTION

Throughout this paper  $G=(V,E)$  is a simple (i.e. finite, undirected, without loops and multiple edges) graph [1]. Let  $co-G = \overline{G}$  denote the complement graph of  $G$ . For  $U \subseteq V$  let  $G(U)$  denote the subgraph of  $G$  induced by  $U$ . By  $G-X$  we mean the graph  $G(V-X)$ , whenever  $X \subseteq V$ , but we often denote it simply by  $G-v$  ( $\forall v \in V$ ) when there is no ambiguity.

If  $v \in V$  is a vertex in  $G$ , the neighborhood  $N_G(v)$  denotes the vertices of  $G-v$  that are adjacent to  $v$ . We write  $N(v)$  when the graph  $G$  appears clearly from the context. The neighborhood of the vertex  $v$  in the complement of the graph  $G$  is denoted by  $\overline{N}(v)$ . For any subset  $S$  of vertices in the graph  $G$  the neighborhood of  $S$  is  $N(S) = \cup_{v \in S} N(v) - S$  and  $N[S] = S \cup N(S)$ . A *stable* (or *independent*) set is a subset of  $V$  with the property that all the vertices are pairwise non-adjacent.

By  $P_n, C_n, K_n$  we mean a chordless path on  $n \geq 3$  vertices, the chordless cycle on  $n \geq 3$  vertices, and the complete graph on  $n \geq 1$  vertices. If  $e=xy \in E$ , we also denote  $x \sim y$ ; we also denote  $x \approx y$  whenever  $x, y$

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are not adjacent in  $G$ . A set  $A$  is totally adjacent (non adjacent) with a set  $B$  of vertices ( $A \cap B = \emptyset$ ) if  $ab$  is (is not) edge, for any  $a$  vertex in  $A$  and any  $b$  vertex in  $B$ ; we note denote  $A \sim B$  ( $A \approx B$ ). A graph  $G$  is  $F$ -free if none of its induced subgraphs is in  $F$ .

The paper is organized as follows. In Section 2 we give preliminary results. In Section 3 we give a characterization of weak-bisplit graphs. In Section 4 we give some applications in optimization problems.

## 2. PRELIMINARY RESULTS

At first, we recall the notion of weak component.

**Definition 1.** ([2],[3],[4]) A set  $A \subset V(G)$  is called a weak set of the graph  $G$  if  $N_G(A) \neq V(G) - A$  and  $G(A)$  are connected. If  $A$  is a weak set, maximal with respect to set inclusion, then  $G(A)$  is called a weak component. For simplicity, the weak component  $G(A)$  will be denoted by  $A$ .

**Definition 2.** ([2],[3],[4]) Let  $G=(V,E)$  be a connected and non-complete graph. If  $A$  is a weak set, then the partition  $\{A, N(A), V-A \cup N(A)\}$  is called a weak decomposition of  $G$  with respect to  $A$ .

The name of "weak component" is justified by the following result.

**Theorem 1.** ([2],[3],[4]) Every connected and non-complete graph  $G=(V,E)$  admits a weak component  $A$  such that

$$G(V - A) = G(N(A) + G(\overline{N}(A))).$$

**Theorem 2.** ([2],[3],[4]) Let  $G=(V,E)$  be a connected and non-complete graph and  $A \subset V$ . Then  $A$  is a weak component of  $G$  if and only if  $G(A)$  is connected and  $N(A) \sim \overline{N}(A)$ .

The next result, based on Theorem 1, ensures the existence of a weak decomposition in a connected and non-complete graph.

**Theorem 3.** If  $G=(V,E)$  is a connected and non-complete graph, then  $V$  admits a weak decomposition  $(A,B,C)$ , such that  $G(A)$  is a weak component and  $G(V-A)=G(B)+G(C)$ .

Theorem 2 provides an  $O(n+m)$  algorithm for building a weak decomposition for a non-complete and connected graph.

## 3. THE RESULTS CONCERNING WEAK-BISPLIT GRAPHS

**Definition 3.** A graph  $G$  is a weak bisplit graph if and only if it has an independent set  $S$  such that every connected component of  $G-S$  is a biclique (i. e. a complete bipartite subgraph).

A graph  $Star_{123}$  and the next graph  $(\{a,b,c,d,e,f,g\}, \{ab,bc,cd,ce,ef,fg\})$  are isomorphic.

A graph is weak bisplit ([7]) if and only if it is  $\{P_7, C_{2k+1}(k \geq 2), Star_{123}\}$ -free.

A graph is bi-cograph ([6]) if and only if it is  $\{P_7, Star_{123}, Sun_4\}$ -free.

It is known that ([7]) a graph is weak-bisplit if and only if it is  $\{P_7, C_{2k+1}(k \geq 2), Star_{123}\}$ -free. Because a  $P_4$ -free graph is  $P_7$ -free, any graph  $\{P_4, C_{2k+1}(k \geq 2), Star_{123}\}$ -free (still called *weak bisplit cograph*) is weak-bisplit.

In [5] the following result is shown, but for a complete presentation we describe it again.

**Theorem 4.** *Let  $G=(V,E)$  be a connected and incomplete graph and  $(A,N,R)$  be a weak decomposition with  $G(A)$*

*the weak component.  $G$  is weak-bisplit cograph if and only if:*

*i)  $A \sim N \sim R$*

*ii)  $G(A), G(N), G(R)$  are weak-bisplit cographs.*

*Proof.* Let  $G$  be a weak-bisplit cograph and  $(A,N,R)$  be a weak decomposition with  $G(A)$  the weak component.

Then  $N \sim R$ , because  $G(A)$  is the weak component. Because  $G$  is  $P_4$ -free,  $A \sim N \sim R$ .

Vice versa, we assume that  $G(A), G(N), G(R)$  are weak-bisplit cographs and  $A \sim N \sim R$ . From ([11]), because

$G(A), G(N), G(R)$  are weak-bisplit cographs and  $A \sim N \sim R$ ,  $G$  is  $P_4$ -free.  $C_{2k+1}(k \geq 2) \not\subset G(A \cup R)$ , because

$G(A), G(R)$  are weak-bisplit cographs and  $G(A \cup R)$  is not connected.  $C_{2k+1}(k \geq 2) \not\subset G(A \cup N)$ , because  $G(A)$ ,

$G(N)$  are weak-bisplit cographs and  $A \sim N$ .  $C_{2k+1}(k \geq 2) \not\subset G(N \cup R)$ , because  $G(N), G(R)$  are weak-bisplit

cographs and  $N \sim R$ .  $C_{2k+1}(k \geq 2) \not\subset G(A \cup N \cup R)$  with  $V(C_{2k+1}) \cap A \neq \Phi$ ,  $V(C_{2k+1}) \cap N \neq \Phi$ ,

$V(C_{2k+1}) \cap R \neq \Phi$ , because  $G(A), G(N), G(R)$  are weak-bisplit cographs and  $A \sim N \sim R$ .  $Star_{123} \not\subset G(A \cup R)$ ,

because  $G(A), G(R)$  are weak bisplit cographs and  $G(A \cup R)$  is not connected.  $Star_{123} \not\subset G(A \cup N)$ , because

$G(A), G(N)$  are weak bisplit cographs and  $A \sim N$ .  $Star_{123} \not\subset G(N \cup R)$ , because  $G(N), G(R)$  are weak-bisplit

cographs and  $N \sim R$ .  $Star_{123} \not\subset G(A \cup N \cup R)$  with  $V(Star_{123}) \cap A \neq \Phi$ ,  $V(Star_{123}) \cap N \neq \Phi$ ,  $V(Star_{123}) \cap R \neq \Phi$ ,

because  $G(A), G(N), G(R)$  are weak-bisplit cographs and  $A \sim N \sim R$ . So  $G$  is weak-bisplit cograph.

#### 4. SOME APPLICATIONS IN OPTIMIZATION PROBLEMS

The aim of the first problem family is to determine a location that minimizes the maximum distance to any other location in the network.

The *eccentricity* of a vertex  $u \in V$  is  $e_G(u) = \max \{d(u, v) : v \in V\}$ .

The *radius* is  $r(G) = \min\{e_G(u) : u \in V\}$ . The *diameter* is  $\text{diam}(G) = \max_{x,y \in V(G)} \{d_G(x, y)\}$ .

The *center*  $C(G)$  of a graph  $G$  is  $C(G) = \{u \in V : r(G) = e_G(u)\}$ .

For each node  $i$ , the local clustering coefficient,  $C_l(i)$ , is simply defined as the fraction of pairs of neighbors of  $i$  that are themselves neighbors. The number of possible links between the neighbors of node  $i$  is simply  $d_i(d_i - 1) / 2$ . The number of favorable connections in the graph  $G(X)$  between neighbors of node  $i$  is denoted by  $n_i(G(X))$ , which means, the vertex degree  $i$  in the induced subgraph by  $X$  ( $X \subseteq V$ ).

Thus we get

$$C_l(i) = \frac{|\{e_{jk} \in E(G) : e_{ij} \in E(G) \wedge e_{ik} \in E(G)\}|}{d_i(d_i - 1)/2} = \frac{n_i(G)}{d_i(d_i - 1)/2}.$$

The global clustering coefficient  $C_l$  is then given by  $C_l = \frac{1}{n} \sum_{i=1}^n C_l(i)$ . A high clustering coefficient  $C_l$  means (in the language of social networks), that two of your friends are likely to be also friends of each other. It also indicates a high redundancy of the network.

I still give the result:

**Theorem 5.** *Let  $G=(V,E)$  be a connected with at least two non-adjacent vertices. If  $G$  is weak-bisplit cograph then the radius of  $G$  is one, the diameter is two and if  $N$  is a clique the center is a clique.*

*Proof.* Let  $(A,N,R)$  a weak decomposition with  $A$  as weak component. For  $\forall a \in A : d(a, n) = 1, d(a, r) = 2, \forall n \in N, \forall r \in R$ . If  $A$  is a clique then  $d(a, a') = 1 \forall a' \in A - \{a\}$ . So,  $e_G(a) = 2$ . For  $\forall n \in N : d(a, n) = d(r, n) = 1, \forall a \in A, \forall r \in R$ . If  $N$  is not a clique then  $\exists n' \in N - \{n\}$  such that  $d(n, n') = 2$ . So  $e_G(n) = 2$ . For  $\forall r \in R : d(r, n) = 1, d(a, r) = 2, \forall a \in A, \forall n \in N$ . If  $R$  is a clique then  $d(r, r') = 2, \forall r' \in R - \{r\}$ . So,  $e_G(r) = 2$ . So,  $r(G)=1$  and  $\text{diam}(G)=2$ . For  $\forall i \in A, c_i = \frac{E(G(N)) + n_i(G(A))}{d_i(d_i - 1)/2}$ . For  $\forall i \in N, c_i = \frac{E(G(A \cup R)) + n_i(G(N))}{d_i(d_i - 1)/2}$ . For  $\forall i \in R, c_i = \frac{E(G(N)) + n_i(G(R))}{d_i(d_i - 1)/2}$ . If  $N$  is a clique the  $C(G)$  is a clique.

#### 5. CONCLUSIONS

In this paper, using weak decomposition, we characterize the weak-bisplit graphs, as well as some of their subclasses. Also, we give some applications in optimization problems.

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