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## FIXED POINTS FOR COMPATIBLE MAPPINGS IN $S$ - METRIC SPACES

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**Abstract.** The purpose of this paper is to prove a general fixed point theorem for two pairs of compatible mappings in  $S$  - metric spaces, which extend Theorem 2 [11] to  $S$  - metric spaces and generalize Theorems 2.2 and 2.7 [20] and other results for a pair of mappings and for a single mapping..

### 1. INTRODUCTION

Let  $f$  and  $g$  be two self mappings of a metric space  $(X, d)$ . Sessa [21] defines  $f$  and  $g$  be weakly commuting if

$$d(fgx, gfx) \leq d(fx, gx), \text{ for all } x \in X.$$

In 1986, Jungck [4] defines  $f$  and  $g$  to be compatible if

$$d(fgx_n, gfx_n) = 0,$$

whenever  $\{x_n\}$  is a sequence in  $X$  such that

$$\lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} gx_n = t \text{ for some } t \in X.$$

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Clearly, commuting mappings are weakly commuting and weakly commuting mappings are compatible, but neither implication is reversible (Example 13 [22] and Example 2.2 [4]).

A generalization of metric space, named  $D$  - metric space, is introduced in [1], [2].

Mustafa and Sims [10], [11] proved that most of the claims concerning the fundamental topological structures on  $D$  - metric spaces are incorrect and introduced appropriate notion of generalized metric spaces, named  $G$  - metric space.

In fact, Mustafa, Sims and other authors studied many fixed point results for self mappings in  $G$  - metric spaces.

Recently in [16], the authors introduced a “generalization” of  $G$  - metric spaces, named  $S$  - metric space. In [3], the authors proved that the notion of  $S$  - metric space is not a generalization of  $G$  - metric space or vice versa. Hence, the notions of  $G$  - metric space and  $S$  - metric space are independent.

Other results in the study of fixed points in  $S$  - metric space are obtained in [6], [9], [14], [15], [17], [19] and in other papers.

Several classical fixed point theorems and common fixed point theorems in metric spaces have been unified in [10], [11], considering a general condition by implicit function.

The study of fixed point for two pairs of compatible mappings satisfying an implicit relation is initiated in [11].

The study of fixed point for mappings satisfying an implicit relation in  $G$  - metric spaces is initiated in [12], [13].

Quite recently, new type of implicit relations in  $S$  - metric spaces is introduced in [17] and [18].

The purpose of this paper is to prove a general fixed point theorems for two pairs of compatible mappings in  $S$  - metric spaces which extend Theorem 2 [11] to  $S$  - metric spaces, generalizing Theorem 2.2 and 2.7 [20] and other results for a pair of mappings and for a single mapping.

## 2. PRELIMINARIES

**Definition 2.1** ([16], [17]). Let  $X$  be a nonempty set. A  $S$  - metric on  $X$  is a function  $S : X^3 \rightarrow \mathbb{R}_+$  such that:

- ( $S_1$ ):  $S(x, y, z) = 0$  if and only if  $x = y = z$ ;
- ( $S_2$ ):  $S(x, y, z) \leq S(x, x, a) + S(y, y, a) + S(z, z, a)$  for all  $x, y, z, a \in X$ .

The pair  $(X, S)$  is called a  $S$  - metric space.

**Example 2.2.** Let  $X = \mathbb{R}$  and  $S(x, y, z) = |x - z| + |y - z|$ . Then,  $S(x, y, z)$  is a  $S$  - metric on  $\mathbb{R}$ , which is named a usual  $S$  - metric on  $X$ .

**Lemma 2.3** ([16], [17]). If  $S$  is a  $S$  - metric on a nonempty set  $X$ , then  $S(x, x, y) = S(y, y, x)$  for all  $x, y \in X$ .

**Definition 2.4.** Let  $(X, S)$  be a  $S$  - metric space. For  $r > 0$  and  $x \in X$  we define the open ball with center  $x$  and radius  $r$ , the set

$$B_S(x, r) = \{y \in X : S(x, x, y) < r\}.$$

The topology induced by  $S$  is the topology determined by the base of all open balls in  $X$ .

**Definition 2.5** ([16], [17]). a) A sequence  $\{x_n\}$  in a  $S$  - metric space  $(X, S)$  is convergent to  $x$ , denoted  $\lim_{n \rightarrow \infty} x_n = x$  or  $x_n \rightarrow x$ , if  $S(x_n, x_n, x) \rightarrow 0$  as  $n \rightarrow \infty$ .

b) A sequence  $\{x_n\}$  in  $(X, S)$  is a Cauchy sequence if  $S(x_n, x_n, x_m) \rightarrow 0$  as  $n, m \rightarrow \infty$ .

c)  $(X, S)$  is complete if every Cauchy sequence is convergent.

**Example 2.6.**  $(X, S)$  with the usual  $S$  - metric is complete.

**Lemma 2.7** ([16], [17]). Let  $(X, S)$  be a  $S$  - metric space. If  $x_n \rightarrow x$  and  $y_n \rightarrow y$ , then  $S(x_n, x_n, y_n) \rightarrow S(x, x, y)$ .

**Lemma 2.8** ([16], [17]). The limit of a convergent sequence is unique.

**Lemma 2.9** ([20]). Let  $(X, S)$  be a  $S$  - metric space. If there exist  $\{x_n\}$  and  $\{y_n\}$  in  $X$  such that  $\lim_{n \rightarrow \infty} S(x_n, x_n, y_n) = 0$  and  $\lim_{n \rightarrow \infty} x_n = t$ , then  $\lim_{n \rightarrow \infty} y_n = t$ .

**Definition 2.10** ([5]). Let  $(X, S)$  and  $(X', S')$  be  $S$  - metric spaces and  $f : (X, S) \rightarrow (X', S')$  be a function. Then  $f$  is continuous at a point  $a \in X$  if every sequence  $\{x_n\}$  in  $X$  with  $S(x_n, x_n, a) \rightarrow 0$  implies  $S(fx_n, fx_n, fa) \rightarrow 0$ .  $f$  is continuous if has this property in all  $x \in X$ .

**Definition 2.11** ([20]). Let  $(X, S)$  be a  $S$  - metric space. A pair  $\{f, g\}$  of self mappings of  $(X, S)$  is said to be compatible if  $\lim_{n \rightarrow \infty} S(fgx_n, fgx_n, gfx_n) = 0$  whenever  $\{x_n\}$  is a sequence in  $X$  such that  $\lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} gx_n = t$  for some  $t \in X$ .

Quite recently, the following two theorems are proved.

**Theorem 2.12** (Theorem 2.2 [20]). Suppose that  $f, g, R$  and  $T$  be self mappings of a complete  $S$  - metric space  $(X, S)$  with  $f(X) \subset$

$T(X)$ ,  $g(X) \subset R(X)$  and the pairs  $\{f, R\}$  and  $\{g, T\}$  are compatible. If

$$(2.1) \quad S(fx, fy, gz) \leq q \max \left\{ \begin{array}{l} S(Rx, Ry, Tz), S(fx, fx, Rx), \\ S(gz, gz, Tz), S(fy, fy, gz) \end{array} \right\}$$

for each  $x, y, z \in X$ , with  $q \in (0, 1)$ .

Then  $f, g, R$  and  $T$  have a unique common fixed point in  $X$  provided that  $R$  and  $T$  are continuous.

**Theorem 2.13** (Theorem 2.7 [20]). *Let  $\{f, R\}$  and  $\{g, T\}$  be compatible mappings of a complete  $S$ -metric space  $(X, S)$  and for all  $x, y, z \in X$  satisfying*

$$(2.2) \quad \begin{aligned} S(fx, fy, gz) &\leq a_1 S(Rx, Ry, Tz) + a_2 S(fx, fx, Tz) + \\ &a_3 S(Rx, Ry, gz) + a_4 S(fy, fy, Tz) + a_5 S(gz, gz, Tz) \end{aligned}$$

where  $a_i \geq 0$ ,  $i = 1, 2, 3, 4, 5$ , are real constants with  $a_1 + 3a_2 + 3a_3 + 3a_4 + a_5 < 1$ .

If  $f(X) \subset T(X)$  and  $g(X) \subset R(X)$  and  $R$  and  $T$  are continuous, then  $f, g, R$  and  $T$  have a unique common fixed point.

**Remark 2.14.** *In the proofs of Theorems 2.12 and 2.13 is used only  $x = y$ . Hence instead inequalities (2.1) and (2.2) we obtain*

$$(2.3) \quad S(fx, fx, gz) \leq q \max \left\{ \begin{array}{l} S(Rx, Rx, Tz), \\ S(fx, fx, Rx), \\ S(gz, gz, Tz) \end{array} \right\}$$

$$(2.4) \quad \begin{aligned} S(fx, fx, gz) &\leq a_1 S(Rx, Rx, Tz) + a_2 S(fx, fx, Tz) + \\ &a_3 S(Rx, Rx, gz) + a_4 S(fx, fx, Tz) + a_5 S(gz, gz, Tz) \end{aligned}$$

**Remark 2.15.** *It is known that  $q(x, y) = G(x, x, y)$  is a quasi-metric on  $X$ . By Lemma 2.3 and  $(S_1)$  we have that  $s(x, y) = S(x, x, y)$  is a symmetric on  $X$ .*

### 3. IMPLICIT RELATIONS

Let  $\mathcal{F}_{CS}$  be the set of all real continuous functions  $F : \mathbb{R}_+^6 \rightarrow \mathbb{R}$  satisfying the following conditions:

$(F_1)$  :  $F$  is nonincreasing in variables  $t_5$  and  $t_6$ ;

$(F_2)$  : There exists  $h \in [0, 1)$  such that for all  $u, v \geq 0$ ,

$(F_{2a})$  :  $F(u, v, v, u, 0, 2u + v) \leq 0$

or

$(F_{2b})$  :  $F(u, v, u, v, 2u + v, 0) \leq 0$

implies  $u \leq hv$ ;

$(F_3)$  :  $F(t, t, 0, 0, t, t) > 0, \forall t > 0$ .

In all the following examples, condition  $(F_1)$  is obviously.

**Example 3.1.**  $F(t_1, \dots, t_6) = t_1 - k \max\{t_2, t_3, t_4, t_5, t_6\}$ , where  $k \in \left[0, \frac{1}{3}\right)$ .

$(F_2)$  :  $(F_{2a})$  : Let  $u, v \geq 0$  and  $F(u, v, v, u, 0, 2u + v) = u - k \max\{u, v, 2u + v\} \leq 0$ . If  $u > v$ , then  $u(1 - 3k) \leq 0$ , a contradiction. Hence,  $u \leq v$ , which implies  $u \leq hv$ , where  $0 \leq h = 3k < 1$ .

$(F_{2b})$  : The proof is similar to the proof of  $(F_{2a})$ .

$(F_3)$  :  $F(t, t, 0, 0, t, t) = t(1 - k) > 0, \forall t > 0$ .

**Example 3.2.**  $F(t_1, \dots, t_6) = t_1 - at_2 - bt_3 - ct_4 - dt_5 - et_6$ , where  $a, b, c, d, e \geq 0$  and  $a + b + c + 3d + 3e < 1$ .

$(F_2)$  :  $(F_{2a})$  : Let  $u, v \geq 0$  and  $F(u, v, v, u, 0, 2u + v) = u - av - bv - cu - e(2u + v) \leq 0$ . If  $u > v$ , then  $u[1 - (a + b + c + 3e)] \leq 0$ , a contradiction. Hence,  $u \leq v$ , which implies  $u \leq h_1v$ , where  $0 \leq h_1 = a + b + c + 3e < 1$ .

$(F_{2b})$  : The proof is similar to the proof of  $(F_{2a})$ , with  $u \leq h_2v$ , where  $0 \leq h_2 = a + b + c + 3d < 1$ .

If  $h = \max\{h_1, h_2\}$ , then  $(F_2)$  is proved.

$(F_3)$  :  $F(t, t, 0, 0, t, t) = t[1 - (a + d + e)] > 0, \forall t > 0$ .

**Example 3.3.**  $F(t_1, \dots, t_6) = t_1 - at_2 - b \max\{t_3, t_4, t_5, t_6\}$ , where  $a, b \geq 0$  and  $a + 3b < 1$ .

$(F_2)$  :  $(F_{2a})$  : Let  $u, v \geq 0$  and  $F(u, v, v, u, 0, 2u + v) = u - av - b \max\{u, v, 2u + v\} \leq 0$ . If  $u > v$ , then  $u[1 - (a + 3b)] \leq 0$ , a contradiction. Hence,  $u \leq v$ , which implies  $u \leq hv$ , where  $0 \leq h = a + 3b < 1$ .

$(F_{2b})$  : The proof is similar to the proof of  $(F_{2a})$ .

$(F_3)$  :  $F(t, t, 0, 0, t, t) = t[1 - (a + b)] > 0, \forall t > 0$ .

**Example 3.4.**  $F(t_1, \dots, t_6) = t_1 - at_2 - bt_3 - ct_4 - d \max\{t_5, t_6\}$ , where  $a, b, c, d \geq 0$  and  $a + b + c + 3d < 1$ .

$(F_2)$  :  $(F_{2a})$  : Let  $u, v \geq 0$  and  $F(u, v, v, u, 0, 2u + v) = u - av - bv - cu - d(2u + v) \leq 0$ . If  $u > v$ , then  $u[1 - (a + b + c + 3d)] \leq 0$ , a contradiction. Hence,  $u \leq v$ , which implies  $u \leq hv$ , where  $0 \leq h = a + b + c + 3d < 1$ .

$(F_{2b})$  : The proof is similar to the proof of  $(F_{2a})$ .

$(F_3)$  :  $F(t, t, 0, 0, t, t) = t[1 - (a + d)] > 0, \forall t > 0$ .

**Example 3.5.**  $F(t_1, \dots, t_6) = t_1 - at_2 - d \max\{t_3, t_4\} - bt_5 - ct_6$ , where  $a, b, c, d \geq 0$  and  $a + d + 3(b + c) < 1$ .

$(F_2) :$   $(F_{2a}) :$  Let  $u, v \geq 0$  and  $F(u, v, v, u, 0, 2u + v) = u - av - d \max\{u, v\} - c(2u + v) \leq 0$ . If  $u > v$ , then  $u[1 - (a + d + 3c)] \leq 0$ , a contradiction. Hence,  $u \leq v$ , which implies  $u \leq h_1 v$ , where  $0 \leq h_1 = a + d + 3c < 1$ .

$(F_{2b}) :$  Let  $u, v \geq 0$  and  $F(u, v, v, u, 0, 2u + v) = u - av - d \max\{u, v\} - b(2u + v) \leq 0$ . If  $u > v$ , then  $u[1 - (a + d + 3b)] \leq 0$ , a contradiction. Hence,  $u \leq v$ , which implies  $u \leq h_2 v$ , where  $0 \leq h_2 = a + d + 3b < 1$ .

If  $h = \max\{h_1, h_2\}$ , then  $(F_2)$  is proved.

$(F_3) :$   $F(t, t, 0, 0, t, t) = t[1 - (a + b + c)] > 0, \forall t > 0$ .

**Example 3.6.**  $F(t_1, \dots, t_6) = t_1 - a(t_5 + t_6) - bt_2 - c \max\{t_3, t_4\}$ , where  $a, b, c \geq 0$  and  $3a + b + c < 1$ .

$(F_2) :$   $(F_{2a}) :$  Let  $u, v \geq 0$  and  $F(u, v, v, u, 0, 2u + v) = u - a(2u + v) - bv - c \max\{u, v\} \leq 0$ . If  $u > v$ , then  $u[1 - (3a + b + c)] \leq 0$ , a contradiction. Hence,  $u \leq v$ , which implies  $u \leq h v$ , where  $0 \leq h = 3a + b + c < 1$ .

$(F_{2b}) :$  The proof is similar to the proof of  $(F_{2a})$ .

$(F_3) :$   $F(t, t, 0, 0, t, t) = t[1 - (2a + b)] > 0, \forall t > 0$ .

**Example 3.7.**  $F(t_1, \dots, t_6) = t_1 - a(t_3 + t_4) - bt_2 - c \max\{t_5, t_6\}$ , where  $a, b, c \geq 0$  and  $2a + b + 3c < 1$ .

$(F_2) :$   $(F_{2a}) :$  Let  $u, v \geq 0$  and  $F(u, v, v, u, 0, 2u + v) = u - a(u + v) - bv - c(2u + v) \leq 0$ . If  $u > v$ , then  $u[1 - (2a + b + 3c)] \leq 0$ , a contradiction. Hence,  $u \leq v$ , which implies  $u \leq h v$ , where  $0 \leq h = 2a + b + 3c < 1$ .

$(F_{2b}) :$  The proof is similar to the proof of  $(F_{2a})$ .

$(F_3) :$   $F(t, t, 0, 0, t, t) = t[1 - (b + c)] > 0, \forall t > 0$ .

**Example 3.8.**  $F(t_1, \dots, t_6) = t_1 - a \max\{t_4 + t_5, t_3 + t_6\} - bt_2$ , where  $a, b \geq 0$  and  $4a + b < 1$ .

$(F_2) :$   $(F_{2a}) :$  Let  $u, v \geq 0$  and  $F(u, v, v, u, 0, 2u + v) = u - a \max\{u, 2u + 2v\} - 2bv \leq 0$ . If  $u > v$ , then  $u[1 - (4a + b)] \leq 0$ , a contradiction. Hence,  $u \leq v$ , which implies  $u \leq h v$ , where  $0 \leq h = 4a + b < 1$ .

$(F_{2b}) :$  The proof is similar to the proof of  $(F_{2a})$ .

$(F_3) :$   $F(t, t, 0, 0, t, t) = t[1 - (a + b)] > 0, \forall t > 0$ .

**Example 3.9.**  $F(t_1, \dots, t_6) = t_1^2 - t_1(at_2 + bt_3 + ct_4) - dt_5t_6$ , where  $a, b, c, d \geq 0$ ,  $a + b + c < 1$  and  $a + d < 1$ .

$(F_2) :$   $(F_{2a}) :$  Let  $u, v \geq 0$  and  $F(u, v, v, u, 0, 2u + v) = u^2 - u(av + bv + cu) \leq 0$ . If  $u > v$ , then  $u^2[1 - (a + b + c)] \leq 0$ , a contradiction. Hence,  $u \leq v$ , which implies  $u \leq hv$ , where  $0 \leq h = \sqrt{a + b + c} < 1$ .

$(F_{2b}) :$  The proof is similar to the proof of  $(F_{2a})$ .

$(F_3) :$   $F(t, t, 0, 0, t, t) = t^2[1 - (a + d)] > 0, \forall t > 0$ .

**Example 3.10.**  $F(t_1, \dots, t_6) = t_1^2 - at_1t_2 - bt_3t_4 - ct_5t_6$ , where  $a, b, c \geq 0, a + b < 1$  and  $a + c < 1$ .

$(F_2) :$   $(F_{2a}) :$  Let  $u, v \geq 0$  and  $F(u, v, v, u, 0, 2u + v) = u^2 - auv - buv \leq 0$ . If  $u > v$ , then  $u^2[1 - (a + b)] \leq 0$ , a contradiction. Hence,  $u \leq v$ , which implies  $u \leq hv$ , where  $0 \leq h = \sqrt{a + b} < 1$ .

$(F_{2b}) :$  The proof is similar to the proof of  $(F_{2a})$ .

$(F_3) :$   $F(t, t, 0, 0, t, t) = t^2[1 - (a + c)] > 0, \forall t > 0$ .

**Example 3.11.**  $F(t_1, \dots, t_6) = t_1 - k \max \left\{ t_2, t_3, t_4, \frac{t_5 + t_6}{3} \right\}$ , where  $k \in [0, 1)$ .

$(F_2) :$   $(F_{2a}) :$  Let  $u, v \geq 0$  and  $F(u, v, v, u, 0, 2u + v) = u - k \max \left\{ u, v, \frac{2u + v}{3} \right\} \leq 0$ . If  $u > v$ , then  $u(1 - k) \leq 0$ , a contradiction. Hence,  $u \leq v$ , which implies  $u \leq hv$ , where  $0 \leq h = k < 1$ .

$(F_{2b}) :$  The proof is similar to the proof of  $(F_{2a})$ .

$(F_3) :$   $F(t, t, 0, 0, t, t) = t(1 - k) > 0, \forall t > 0$ .

#### 4. MAIN RESULTS

**Theorem 4.1.** Let  $f, g, R$  and  $T$  be self mappings of a complete  $S$  - metric space  $(X, S)$  with

1)  $f(X) \subset T(X)$  and  $g(X) \subset R(X)$ ,

2)  $R$  and  $T$  are continuous,

and

$$(4.1) \quad F \left( \begin{array}{l} S(fx, fx, gy), S(Rx, Rx, Ty), S(fx, fx, Rx), \\ S(gy, gy, Ty), S(fx, fx, Ty), S(gy, gy, Rx) \end{array} \right) \leq 0$$

for all  $x, y \in X$  and some  $F \in \mathcal{F}_{CS}$ .

If  $(f, R)$  and  $(g, T)$  are compatible, then  $f, g, R$  and  $T$  have a unique common fixed point.

*Proof.* Let  $x_0$  be an arbitrary point of  $X$ . Since  $f(X) \subset T(X)$ , there exists  $x_1 \in X$  such that  $fx_0 = Tx_1$  and also, as  $gx_1 \in R(X)$ , we choose  $x_2 \in X$  such that  $gx_1 = Rx_2$ . Continuing this process, if

$x_{2n+1} \in X$  is chosen such that  $fx_{2n} = Tx_{2n+1}$  and  $x_{2n+2} \in X$  such that  $gx_{2n+1} = Rx_{2n+2}$ , we obtain a sequence  $\{y_n\}$  in  $X$  such that

$$y_{2n} = fx_{2n} = Tx_{2n+1} \text{ and } y_{2n+1} = gx_{2n+1} = Rx_{2n+2}.$$

By (4.1) for  $x = x_{2n}$  and  $y = x_{2n+1}$  we have

$$(4.2) \quad F \left( \begin{array}{c} S(fx_{2n}, fx_{2n}, gx_{2n+1}), S(Rx_{2n}, Rx_{2n}, Tx_{2n+1}), \\ S(fx_{2n}, fx_{2n}, Rx_{2n}), S(gx_{2n+1}, gx_{2n+1}, Tx_{2n+1}), \\ S(fx_{2n}, fx_{2n}, Tx_{2n+1}), S(gx_{2n+1}, gx_{2n+1}, Rx_{2n}) \end{array} \right) \leq 0$$

$$F \left( \begin{array}{c} S(y_{2n}, y_{2n}, y_{2n+1}), S(y_{2n-1}, y_{2n-1}, y_{2n}), \\ S(y_{2n}, y_{2n}, y_{2n-1}), S(y_{2n+1}, y_{2n+1}, y_{2n}), \\ 0, S(y_{2n+1}, y_{2n+1}, y_{2n-1}) \end{array} \right) \leq 0$$

By Lemma 2.3,

$$\begin{aligned} S(y_{2n}, y_{2n}, y_{2n-1}) &= S(y_{2n-1}, y_{2n-1}, y_{2n}), \\ S(y_{2n+1}, y_{2n+1}, y_{2n}) &= S(y_{2n}, y_{2n}, y_{2n+1}). \end{aligned}$$

By  $(S_2)$  and Lemma 2.3 we have

$$\begin{aligned} S(y_{2n+1}, y_{2n+1}, y_{2n-1}) &\leq 2S(y_{2n+1}, y_{2n+1}, y_{2n}) + S(y_{2n-1}, y_{2n-1}, y_{2n}) \\ &= 2S(y_{2n}, y_{2n}, y_{2n+1}) + S(y_{2n-1}, y_{2n-1}, y_{2n}). \end{aligned}$$

Then, by (4.2) we obtain

$$F \left( \begin{array}{c} S(y_{2n}, y_{2n}, y_{2n+1}), S(y_{2n-1}, y_{2n-1}, y_{2n}), \\ S(y_{2n-1}, y_{2n-1}, y_{2n}), S(y_{2n}, y_{2n}, y_{2n+1}), \\ 0, 2S(y_{2n}, y_{2n}, y_{2n+1}) + S(y_{2n-1}, y_{2n-1}, y_{2n}) \end{array} \right) \leq 0$$

By  $(F_{2a})$  we obtain

$$S(y_{2n}, y_{2n}, y_{2n+1}) \leq hS(y_{2n-1}, y_{2n-1}, y_{2n}).$$

If  $x = x_{2n}$  and  $y = x_{2n-1}$ , by (4.1) we obtain

$$(4.3) \quad F \left( \begin{array}{c} S(fx_{2n}, fx_{2n}, gx_{2n-1}), S(Rx_{2n}, Rx_{2n}, Tx_{2n-1}), \\ S(fx_{2n}, fx_{2n}, Rx_{2n}), S(gx_{2n-1}, gx_{2n-1}, Tx_{2n-1}), \\ S(fx_{2n}, fx_{2n}, Tx_{2n-1}), 0 \end{array} \right) \leq 0$$

$$F \left( \begin{array}{c} S(y_{2n}, y_{2n}, y_{2n-1}), S(y_{2n-1}, y_{2n-1}, y_{2n-2}), \\ S(y_{2n}, y_{2n}, y_{2n-1}), S(y_{2n-1}, y_{2n-1}, y_{2n-2}), \\ S(y_{2n}, y_{2n}, y_{2n-2}), 0 \end{array} \right) \leq 0$$

By  $(S_2)$  we have

$$S(y_{2n}, y_{2n}, y_{2n-2}) \leq 2SS(y_{2n-1}, y_{2n-1}, y_{2n}) + S(y_{2n-2}, y_{2n-2}, y_{2n}).$$



By (4.3) and Lemma 2.3 we obtain

$$F \left( \begin{array}{c} S(y_{2n-1}, y_{2n-1}, y_{2n}), S(y_{2n-2}, y_{2n-2}, y_{2n-1}), \\ S(y_{2n-1}, y_{2n-1}, y_{2n}), S(y_{2n-1}, y_{2n-1}, y_{2n}), \\ 2S(y_{2n-1}, y_{2n-1}, y_{2n}) + S(y_{2n-2}, y_{2n-2}, y_{2n-1}), 0 \end{array} \right) \leq 0.$$

By  $(F_{2b})$  we obtain

$$S(y_{2n-1}, y_{2n-1}, y_{2n}) \leq hS(y_{2n-2}, y_{2n-2}, y_{2n-1}).$$

Hence for all  $n \in \mathbb{N}$  we have

$$S(y_n, y_n, y_{n-1}) \leq hS(y_{n-1}, y_{n-1}, y_n)$$

for all  $n = 1, 2, \dots$ , which implies

$$S(y_n, y_n, y_{n-1}) \leq h^n S(y_1, y_1, y_0).$$

By a routine calculation, see for example [17], we obtain that  $\{y_n\}$  is a Cauchy sequence. Since  $(X, S)$  is complete, there exists  $z \in X$  such that

$$\lim_{n \rightarrow \infty} f x_n = \lim_{n \rightarrow \infty} T x_{2n+1} = \lim_{n \rightarrow \infty} g x_{2n+1} = \lim_{n \rightarrow \infty} R x_{2n+2} = z.$$

Suppose that  $R$  is continuous. Then

$$\lim_{n \rightarrow \infty} R f x_{2n} = R \lim_{n \rightarrow \infty} f x_{2n} = R z$$

and

$$\lim_{n \rightarrow \infty} R^2 x_{2n+2} = R z.$$

Since  $(f, R)$  are compatible, then by  $(S_3)$

$$S(f R x_{2n}, f R x_{2n}, R z) \leq 2S(f R x_{2n}, f R x_{2n}, R f x_{2n}) + S(R z, R z, R f x_{2n}).$$

Letting  $n$  tend to infinity we obtain

$$\lim_{n \rightarrow \infty} S(f R x_n, f R x_n, R z) = 0.$$

By Lemma 2.9,

$$\lim_{n \rightarrow \infty} f R x_n = R z.$$

By (4.1) for  $x = R x_{2n}$ ,  $y = x_{2n+1}$ , we have

$$F \left( \begin{array}{c} S(f R x_{2n}, f R x_{2n}, g x_{2n+1}), S(R^2 x_{2n}, R^2 x_{2n}, T x_{2n+1}), \\ S(f R x_{2n}, f R x_{2n}, R^2 x_{2n}), S(g x_{2n+1}, g x_{2n+1}, T x_{2n+1}), \\ S(f R x_{2n}, f R x_{2n}, T x_{2n+1}), S(g x_{2n+1}, g x_{2n+1}, R^2 x_{2n}) \end{array} \right) \leq 0.$$

Letting  $n$  tend to infinity by Lemma 2.3, we obtain

$$F(S(R z, R z, z), S(R z, R z, z), 0, 0, S(R z, R z, z), S(z, z, R z)) \leq 0.$$

By Lemma 2.3,

$$S(z, z, Rz) = S(Rz, Rz, z).$$

Hence,

$F(S(Rz, Rz, z), S(Rz, Rz, z), 0, 0, S(Rz, Rz, z), S(Rz, Rz, z)) \leq 0$ ,  
a contradiction of  $(F_4)$  if  $S(Rz, Rz, z) > 0$ . Hence,  $S(Rz, Rz, z) = 0$   
and by  $(S_1)$ ,  $z = Rz$ .

In a similar way, since  $T$  is continuous, we obtain

$$\lim_{n \rightarrow \infty} T^2 x_{2n+1} = Tz \text{ and } \lim_{n \rightarrow \infty} Tg x_{2n+1} = Tz$$

and by compatibility of  $g$  and  $T$  we obtain

$$\lim_{n \rightarrow \infty} gT x_{2n+1} = Tz.$$

By (4.1) for  $x = x_{2n}$  and  $y = T x_{2n+1}$  we obtain that

$$F \left( \begin{array}{l} S(fx_{2n}, fx_{2n}, gT x_{2n+1}), S(Rx_{2n}, Rx_{2n}, T^2 x_{2n+1}), \\ S(fx_{2n}, fx_{2n}, Rx_{2n}), S(gT x_{2n+1}, gT x_{2n+1}, T^2 x_{2n+1}), \\ S(fx_{2n}, fx_{2n}, T^2 x_{2n+1}), S(gT x_{2n+1}, gT x_{2n+1}, Rx_{2n}) \end{array} \right) \leq 0.$$

Letting  $n$  tend to infinity we obtain

$$F(S(z, z, Tz), S(z, z, Tz), 0, 0, S(z, z, Tz), S(z, z, Tz)) \leq 0,$$

a contradiction of  $(F_3)$  if  $S(z, z, Tz) > 0$ . Hence,  $S(z, z, Tz) = 0$ ,  
which implies, by  $(S_1)$  that  $z = Tz$ .

Also, by (4.1) for  $x = z$  and  $y = x_{2n+1}$  we obtain

$$F \left( \begin{array}{l} S(fz, fz, gx_{2n+1}), S(Rz, Rz, T x_{2n+1}), \\ S(fz, fz, Rz), S(gx_{2n+1}, gx_{2n+1}, T x_{2n+1}), \\ S(fz, fz, T x_{2n+1}), S(gx_{2n+1}, gx_{2n+1}, Rz) \end{array} \right) \leq 0,$$

$$F(S(fz, fz, z), 0, S(fz, fz, z), 0, S(fz, fz, z), 0) \leq 0.$$

By  $(F_1)$  we have

$$F(S(fz, fz, z), 0, S(fz, fz, z), 0, 2S(fz, fz, z), 0) \leq 0.$$

By  $(F_{2b})$ ,

$$S(fz, fz, z) = 0$$

which implies

$$z = fz.$$

By (4.1) for  $x = z$  and  $y = z$  we obtain that

$$F \left( \begin{array}{l} S(fz, fz, gz), S(Rz, Rz, Tz), S(fz, fz, Rz), \\ S(gz, gz, Tz), S(fz, fz, Tz), S(gz, gz, Rz) \end{array} \right) \leq 0,$$

$$F(S(z, z, gz), 0, 0, S(z, z, gz), 0, S(z, z, gz)) \leq 0,$$

By  $(F_1)$  we obtain

$$F(S(z, z, gz), 0, 0, S(z, z, gz), 0, 2S(z, z, gz)) \leq 0.$$

By  $(F_{2a})$ ,  $S(z, z, gz) = 0$  which implies by  $(S_1)$ ,  $z = gz$ . Hence,  $z$  is a common fixed point of  $f, g, R$  and  $T$ .

Suppose that  $u$  is other common fixed point of  $f, g, R$  and  $T$ . By (4.1) we obtain

$$F\left(\begin{array}{l} S(fu, fu, gv), S(Ru, Ru, Tv), S(fu, fu, Ru), \\ S(gv, gv, Tv), S(fu, fu, Tv), S(gv, gv, Ru) \end{array}\right) \leq 0,$$

$$F(S(u, u, v), S(u, u, v), 0, 0, S(u, u, v), S(v, v, u)) \leq 0.$$

By Lemma 2.3,

$$S(u, u, v) = S(v, v, u).$$

Hence,

$$F(S(u, u, v), S(u, u, v), 0, 0, S(u, u, v), S(u, u, v)) \leq 0,$$

a contradiction of  $(F_4)$ . Hence,  $S(u, u, v) = 0$ . By  $(S_1)$ ,  $u = v$ .  $\square$

By Theorem 4.1 and Example 3.11 we obtain

**Theorem 4.2.** *Let  $f, g, R$  and  $T$  be self mappings of a complete  $S$  - metric space  $(X, S)$  with*

- 1)  $f(X) \subset T(X)$  and  $g(X) \subset R(X)$ ,
  - 2)  $R$  and  $T$  are continuous,
- and

$$S(fx, fx, gy) \leq q \max \left\{ \begin{array}{l} S(Rx, Rx, Ty), \\ S(fx, fx, Rx), \\ S(gy, gy, Ty), \\ \frac{S(fx, fx, Ty) + S(gy, gy, Rx)}{3} \end{array} \right\}$$

for all  $x, y \in X$ , where  $q \in (0, 1)$ .

If  $(f, R)$  and  $(g, T)$  are compatible, then  $f, g, R$  and  $T$  have a unique common fixed point.

**Corollary 4.3.** *Let  $f, g, R$  and  $T$  be self mappings of a complete  $S$  - metric space  $(X, S)$  with*

- 1)  $f(X) \subset T(X)$  and  $g(X) \subset R(X)$ ,
- and

$$S(fx, fx, gy) \leq q \max \{S(Rx, Rx, Ty), S(fx, fx, Rx), S(gy, gy, Ty)\}$$

for all  $x, y \in X$ , where  $q \in (0, 1)$ .

If  $(f, R)$  and  $(g, T)$  are compatible, then  $f, g, R$  and  $T$  have a unique common fixed point.

*Proof.* The proof follows by Theorem 4.2 because

$$\max \left\{ S(Rx, Rx, Ty), S(fx, fx, Rx), S(gy, gy, Ty) \right\} \leq \max \left\{ \frac{S(Rx, Rx, Ty), S(fx, fx, Rx), S(gy, gy, Ty), S(fx, fx, Ty) + S(gy, gy, Rx)}{3} \right\}.$$

□

**Remark 4.4.** *This corollary is a new form of Theorem 2.12.*

**Theorem 4.5.** *Let  $f, g, R$  and  $T$  be self mappings of a complete  $S$ -metric space  $(X, S)$  with*

1)  $f(X) \subset T(X)$  and  $g(X) \subset R(X)$ ,

2)  $R$  and  $T$  are continuous,

and

$$S(fx, fx, gy) \leq a_1 S(Rx, Rx, Ty) + a_2 S(fx, fx, Rx) + a_3 S(gy, gy, Ty) + a_4 S(fx, fx, Ty) + a_5 S(gy, gy, Rx),$$

where  $a_1, \dots, a_5 \geq 0$  and  $a_1 + a_2 + a_3 + 3a_4 + 3a_5 < 1$ , for all  $x, y \in X$ .

*If  $(f, R)$  and  $(g, T)$  are compatible, then  $f, g, R$  and  $T$  have a unique common fixed point.*

*Proof.* The proof follows by Theorem 4.1 and Example 3.2. □

**Corollary 4.6.** *Let  $f, g, R$  and  $T$  be self mappings of a complete  $S$ -metric space  $(X, S)$  with*

1)  $f(X) \subset T(X)$  and  $g(X) \subset R(X)$ ,

2)  $R$  and  $T$  are continuous,

and

$$S(fx, fx, gy) \leq a_1 S(Rx, Rx, Ty) + a_2 S(gy, gy, Ty) + a_3 S(fx, fx, Ty) + a_4 S(gy, gy, Rx),$$

for all  $x, y \in X$ , where  $a_1, \dots, a_4 \geq 0$  and  $a_1 + a_2 + 3a_3 + a_4 < 1$ .

*If  $(f, R)$  and  $(g, T)$  are compatible, then  $f, g, R$  and  $T$  have a unique common fixed point.*

*Proof.* The proof is similar to the proof of Corollary 4.3. □

If  $R$  and  $T$  are identity mappings on  $X$  by Theorem 4.1 we obtain

**Theorem 4.7.** *Let  $f$  and  $g$  be self mappings of a complete  $S$ -metric space  $(X, S)$  such that*

$$F \left( \begin{array}{c} S(fx, fx, gy), S(x, x, y), S(fx, fx, x), \\ S(gy, gy, y), S(fx, fx, y), S(gy, gy, x) \end{array} \right) \leq 0$$

for all  $x, y \in X$  and some  $F \in \mathcal{F}_{CS}$ .

*Then  $f$  and  $g$  have a unique common fixed point.*

By Theorem 4.1 and Example 3.11 we obtain

**Theorem 4.8.** *Let  $(X, S)$  be a complete  $S$  - metric space and  $f, g$  be self mappings of  $X$  such that*

$$S(fx, fx, gy) \leq q \max \left\{ \begin{array}{l} S(x, x, y), S(fx, fx, x), S(gy, gy, y), \\ \frac{S(fx, fx, y) + S(gy, gy, x)}{3} \end{array} \right\}$$

for all  $x, y \in X$  and some  $F \in \mathcal{F}_{CS}$ .

Then  $f$  and  $g$  have a unique common fixed point.

If  $f = g$ , then by Theorem 4.7 we obtain

**Theorem 4.9.** *Let  $(X, S)$  be a complete  $S$  - metric space and  $f : X \rightarrow X$  be a mapping nonincreasing in  $t_6$  such that*

$$F \left( \begin{array}{l} S(fx, fx, fy), S(x, x, y), S(fx, fx, x), \\ S(fy, fy, y), S(fx, fx, y), S(fy, fy, x) \end{array} \right) \leq 0$$

for all  $x, y \in X$  and some  $F$  satisfying properties  $(F_1)$ ,  $(F_{2a})$  and  $(F_3)$ .

Then  $f$  has a unique fixed point.

By Example 3.11 we obtain a new Ćirić type theorem in  $S$  - metric spaces.

**Corollary 4.10.** *Let  $(X, S)$  be a complete  $S$  - metric space and  $f : X \rightarrow X$  be a mapping such that*

$$S(fx, fx, fy) \leq q \max \left\{ \begin{array}{l} S(x, x, y), S(fx, fx, x), S(fy, fy, y), \\ \frac{S(fx, fx, y) + S(fy, fy, x)}{3} \end{array} \right\}$$

for all  $x, y \in X$  and  $q \in [0, 1)$ .

Then  $f$  has a unique fixed point.

**Remark 4.11.** 1) By Examples 3.1 - 3.8 we obtain all the results from [9].

2) By Example 3.2 we obtain Corollary 2.19 [17], Theorems 2.3, 2.4 [13] and Theorems 3.2, 3.3, 3.4 [14].

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