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ON RANDERS SPACES OF CONSTANT CURVATURE

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Abstract. In this paper we study the Randers manifolds of constant curvature induced by generalized Sasakian space forms with different almost contact structures.

1. INTRODUCTION

A Finsler metric $L(x, y)$ on an n -dimensional manifold M^n is called an (α, β) -metric[9] $L(\alpha, \beta)$ if L is positively homogeneous function of α and β of degree one, where $\alpha^2 = a_{ij}(x)y^i y^j$ is a Riemannian metric and $\beta = b_i(x)y^i$ is a 1-form on M^n . Randers metrics are simplest (α, β) -metrics, which are expressed in the form $F = \alpha + \beta$ with $\|\beta\| < 1$. In Finsler geometry it is difficult to make classification of Finsler metrics of constant curvature, but for the case of special Finsler metrics like Randers metrics, a classification theorem was given by Yasuda and Shimada[16] and Matsumoto and Shimada[14]. But Bao and Robles[8] found some errors in both the proofs and they gave a corrected version of Yasuda and Shimada theorem which characterises Randers spaces of constant curvature.

Keywords and phrases: Randers metric, constant flag curvature, a -Sasakian, b -Kenmotsu, co-symplectic, ϕ -sectional curvature, generalized Sasakian space forms, constant negative curvature.

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Bejancu and Farran [6] gave a classification theorem for a class of proper Randers manifolds of positive constant flag curvature. They have shown that a Sasakian space form induces a Randers space of positive constant curvature. Same authors in [5] proved that under certain natural conditions, Randers manifolds of positive constant flag curvature are diffeomorphic to odd dimensional spheres. Hasegawa et al.[11] established that there are other almost contact structures that induce Randers space of constant negative flag curvature and constant curvature $K = 0$. Motivated by the above results, in this paper we investigate a class of Randers manifolds induced by generalized Sasakian space forms with a -Sasakian, b -Kenmotsu and co-symplectic structures.

2. PRELIMINARIES

2.1. Randers Metrics. A Finsler metric F on a manifold M is a function $F : TM \rightarrow (0, \infty)$ such that

- (1) F is C^∞ on $TM - \{0\}$
- (2) $F_x = F|_{T_xM}$ is a Minkowski norm on T_xM :
 $F(x, \lambda y) = \lambda F(x, y)$ for $\lambda > 0$

The fundamental tensor field is positive definite, $(g_{ij}(x, y)) > 0$, where $g_{ij} = \frac{1}{2} \frac{\partial^2 F^2}{\partial y^i \partial y^j}$.

Randers metrics are among the simplest Finsler metrics. Let $F = \alpha + \beta$ be a Randers metric on a manifold M^n , where $\alpha^2 = a_{ij}(x)y^i y^j$ is a Riemannian metric and $\beta = b_i(x)y^i$ is a 1-form on M^n with $\|\beta\| < 1$ [9]. The space $R^n = (M^n, \alpha)$ is called the associated Riemannian space with $F^n = (M^n, L(\alpha, \beta))$. The spray coefficients G^i of F are given by

$$(1) \quad G^j = \frac{1}{4} g^{jh} \left(\frac{\partial^2 F^2}{\partial y^h \partial x^k} y^k - \frac{\partial F^2}{\partial x^h} \right), G_j^i = \frac{\partial G^i}{\partial y^j}.$$

The spray coefficients G^i of F and $G^i \alpha$ of α are related by [17]

$$(2) \quad G^i = G_\alpha^i + P y^i + Q^i, \text{ where}$$

$$P = \frac{e_{00}}{2F} - s_0, Q^i = \alpha s_0^i,$$

$$e_{ij} = r_{ij} + b_i s_j + b_j s_i,$$

$$(3) \quad r_{ij} = \frac{1}{2}(b_{i|j} + b_{j|i}), s_{ij} = \frac{1}{2}(b_{i|j} - b_{j|i}),$$

$$s_j^i = a^{ih} s_{hj}, s_j = b_i s_j^i = b^i s_{ij},$$

$$e_{00} = e_{ij} y^i y^j, s_0 = s_i y^i, s_0^i = s^i y^j,$$

where $|$ denote the covariant differentiation with respect to the Levi-Civita connection $\gamma_{jk}^i(x)$ of R^n .

The spray coefficients G_j^i are used to define Riemann tensor R_j^i as follows.

$$(4) \quad R_j^i = l^h \left(\frac{\delta}{\delta x^j} \left(\frac{G_h^k}{F} \right) - \frac{\delta}{\delta x^h} \left(\frac{G_j^k}{F} \right) \right), l^h = \frac{y^h}{F},$$

where

$$(5) \quad \frac{\delta}{\delta x^i} = \frac{\partial}{\partial x^i} - G_i^j \frac{\partial}{\partial y^j}.$$

A Finsler metric F has constant flag curvature λ if

$$(6) \quad R^i_k = \lambda F^2 h^i_k,$$

where $h^i_k = h_{jk} g^{ij}, h_{ij} = (g_{ij} - l_i l_j), l_i = l^j g_{ij}$.

The Ricci curvature and Ricci scalar are defined by

$$(7) \quad Ric = R^i_i, \quad R = \frac{1}{n+1} Ric.$$

A Finsler metric F has constant Ricci curvature if

$$(8) \quad Ric = (n-1)\lambda F^2.$$

2.2. Almost contact metric structures and Generalized Sasakian space forms.

An n - dimensional Riemannian manifold (M, α) is said to be an almost contact metric manifold if there exist on M , a $(1,1)$ tensor field ϕ , a unit vector field ξ , a 1-form η satisfying

$$(9) \quad \varphi^2 = -I + \eta \otimes \xi, \eta(\xi) = 1, \varphi\xi = 0, \eta \circ \varphi = 0.$$

$$(10) \quad a(\phi X, \phi Y) = a(X, Y) - \eta(X)\eta(Y),$$

$$(11) \quad a(X, \phi Y) + a(\phi X, Y) = 0, \forall X, Y \in TM.$$

We denote an almost contact metric manifold by $M(\phi, \xi, \eta, a)$. An almost contact metric manifold is called a contact metric manifold if $d\eta = \Phi$, where Φ is the fundamental 2-form on M given by $\Phi(X, Y) = a(X, \phi Y)$. An almost contact metric manifold $M(\phi, \xi, \eta, a)$ is called

- Sasakian manifold if

$$(12) \quad (\nabla_X \phi)Y = a(X, Y)\xi - \eta(Y)X,$$

- Kenmotsu manifold if

$$(13) \quad (\nabla_X \phi)Y = -a(X, Y)\xi + \eta(Y)\phi X,$$

- a (a,b)-trans-Sasakian manifold if

$$(14) \quad (\nabla_X \phi)Y = a(a(X, Y)\xi - \eta(Y)X) + b(a(\phi X, Y)\xi - \eta(Y)\phi X),$$

where a and b are some functions.

In a trans-Sasakian manifold M , the following hold:

$$(15) \quad (\nabla_X \xi) = -\phi X + \beta(X - \eta(X)\xi), \quad (\nabla_X \eta)Y = a(\nabla_X \xi, Y), \quad \forall X \in TM.$$

If $b = 0$, M is said to be an a - Sasakian manifold and Sasakian manifolds are the examples of a - Sasakian manifolds with $a = 1$.

If $a = 0$, M is said to be an b - Kenmotsu manifold and Kenmotsu manifolds are examples of b - Kenmotsu manifolds with $b = 1$.

If X is orthonormal to ξ then the plane section $\{X, \phi X\}$ is called ϕ -section and the curvature associated with this section is called ϕ -sectional curvature which is given by

$$(16) \quad H(X) = K(X, \phi X) = R(X, \phi X, X, \phi X).$$

A Sasakian manifold of constant ϕ -sectional curvature c is called a Sasakian space form $M(c)$.

A Kenmotsu manifold of constant ϕ -sectional curvature c is called a Kenmotsu space form.

An almost contact metric manifold (M, ϕ, ξ, η, a) is called a generalized Sasakian space forms if the curvature tensor R is given by

$$(17) \quad \begin{aligned} R(X, Y)Z &= f_1\{g(Y, Z)X - g(X, Z)Y\} \\ &+ f_2\{g(X, \phi Z)\phi Y - g(Y, \phi Z)\phi X + 2g(X, \phi Y)\phi Z\} \\ &+ f_3\{\eta(X)\eta(Z)Y - \eta(Y)\eta(Z)X + g(X, Z)\eta(Y)\xi - g(Y, Z)\eta(X)\xi\}, \end{aligned}$$

where f_1, f_2, f_3 differential functions on M .

Sasakian space forms are examples of generalized Sasakian space forms with constant functions $f_1 = \frac{c+3}{4}, f_2 = f_3 = \frac{c-1}{4}$.

3. RANDERS SPACES OF CONSTANT CURVATURE INDUCED BY GENERALIZED SASAKIAN SPACE FORMS

Yasuda-Shimada[16] gave the following classical theorem for Randers spaces of constant curvature.

Theorem 1. *Let $F^n = (M, F = \alpha + \beta), \alpha = \sqrt{a_{ij}(x)y^i y^j}, \beta = b_i(x)y^i$ be a Randers space. Then*

[A] *F^n has constant negative flag curvature λ and $\text{curl}_{b_i} = b^j(b_{j|i} - b_{i|j}) = 0$ if and only if the Riemannian space (M, α) is of negative*

constant sectional curvature $-\lambda^2$. $b_{i|j} = \lambda(a_{ij} - b_i b_j)$,

[B] F^n is flat (i.e. $\lambda = 0$) and $\text{curl}_{b_i} = 0$ if and only if it is locally Minkowski,

[C] F^n has constant positive flag curvature λ and $\text{curl}_{b_i} = 0$ if and only if the Riemannian curvature tensor R of the Riemannian space (M, α) satisfies

$$\begin{aligned} R_{hikj} &= \lambda(b_h b_j a_{ik} - b_k b_h a_{ij}) + \lambda(b_i b_k a_{hj} - b_i b_j a_{kh}) \\ &+ \lambda(1 - \|b\|^2)(a_{hj} a_{ik} - a_{kh} a_{ij}) \\ &+ 2b_{i|h} b_{j|k} - b_{i|k} b_{h|j} - b_{i|j} b_{k|h} \end{aligned}$$

and $\|b\|$ is a constant and $b_{j|k} + b_{k|j} = 0$.

In an α -Sasakian manifold,

$$(18) \quad \eta_{i|j} = -a\phi_i^k a_{jk},$$

$$(19) \quad \eta_{i|j} + \eta_{j|i} = 0,$$

$$(20) \quad \eta_{i|j} - \eta_{j|i} = 2a\phi_i^j a_{jk},$$

$$(21) \quad \eta_{i|j} \xi^i = \eta_{i|j} \xi^j = 0,$$

$$(22) \quad \xi^i (\eta_{i|j} - \eta_{j|i}) = 0.$$

The expression for R in a generalized Sasakian space form is

$$\begin{aligned} R_{hijk} &= f_1 (a_{hj} a_{ik} - a_{hk} a_{ij}) - \frac{f_2}{a^2} (\eta_{i|j} \eta_{h|k} - \eta_{h|j} \eta_{i|k} + 2\eta_{i|h} \eta_{j|k}) + \\ (23) \quad &f_3 (\eta_i \eta_j a_{hk} - \eta_h \eta_j a_{ik} + \eta_h \eta_k a_{ij} - \eta_i \eta_k a_{hj}). \end{aligned}$$

Suppose M is an odd dimensional almost contact metric manifold with almost contact metric structure (ϕ, ξ, η, a) . Then we have a Riemannian metric a and a 1-form $\eta = \eta_i(x) dx^i$ on M . We can construct in a natural way a Randers metric $F = \alpha + \beta$, where $\alpha = \sqrt{a_{ij}(x) y^i y^j}$, $\beta = c\eta_i(x) y^i$, with $0 < c < 1$. Then F is a Randers metric on M which is positive definite. This is because $\|b\|^2 = c^2 \|\eta\|^2 = c^2 < 1$. Further we have

$$(1) \quad \|b\| = c, \text{ a constant.}$$

$$(2) \quad (\nabla_{\phi Y} b)Y = c(\nabla_{\phi Y} \eta)Y = -ac a(\phi Y, \phi Y) \neq 0. \text{ i.e. } b \text{ is not parallel.}$$

$$(3) \quad b_{i|j} + b_{j|i} = c(\eta_{i|j} + \eta_{j|i}) = 0, \text{ follows from 19.}$$

Theorem 2 (P. Alegre and A. Carriazo, 2008). *If $M(f_1, f_2, f_3)$ is an α -Sasakian generalized Sasakian space form, then $\xi(a) = 0$ and $f_1 - f_3 = a^2$ holds. Further if M is connected then a is a constant.*

If we choose $f_2 = f_3 = -c^2a^2$, then from the above theorem, $f_1 = -a^2(1 - c^2)$. The equation (23) takes the form

$$\begin{aligned}
 R_{hijk} &= \lambda(1 - \|b\|^2)(a_{hj}a_{ik} - a_{hk}a_{ij}) \\
 (24) \quad &+ \lambda(2\eta_{i|h}\eta_{j|k} - b_{i|j}b_{k|h} - b_{h|j}b_{i|k}) \\
 &+ \lambda(b_ib_ka_{hj} + b_jb_ha_{ik} - b_ib_ja_{hk} - b_hb_ka_{ij}), \text{ with } \lambda = a^2.
 \end{aligned}$$

Thus by theorem 1, we conclude that

Theorem 3. *Let $(M, F = \alpha + \beta)$ be the Randers space induced by a connected α -Sasakian generalized Sasakian space form $M(f_1, f_2, f_3)$, where $\alpha = \sqrt{a_{ij}(x)y^iy^j}$, $\beta = c\eta_i(x)y^i$, where $0 < c < 1$. If $f_2 = f_3 = -c^2a^2$ then the Randers space (M, F) is a Randers space of positive constant curvature $\lambda = a^2$.*

This theorem holds for $c = 1$ also. But the Randers metric is not positive definite. Randers-space of constant curvature 1. We define on M ,

$$\begin{aligned}
 (25) \quad a_{ij}^* &= a^2a_{ij} \\
 b_i^*(x) &= ab_i(x)
 \end{aligned}$$

Then the function $F^*(x, y) = aF(x, y)$ is a Randers metric on TM^0 . Now from $g_{ij} = \frac{1}{2} \frac{\partial F^2}{\partial y^i \partial y^j}$, we get

$$\begin{aligned}
 (26) \quad g_{ij}^* &= a^2g_{ij}, g^{ij*} = \frac{1}{a^2}g^{ij}, l_i^* = al_i, l^{i*} = \frac{1}{a}l^i, \\
 h_{ij}^* &= a^2h_{ij}, h^{ij*} = \frac{1}{a^2}h^{ij}, h^{i*}_j = h^i_j.
 \end{aligned}$$

From (1),(4) and (6), it follows that the spray coefficients G^{*i} and the Riemann tensor R^{*i}_j are given by

$$(27) \quad G^{i*} = G^i, R^{i*}_j = R^i_j.$$

If F is a Randers metric of constant curvature a^2 , then $R^i_j = a^2F^2h^i_j$. Therefore $R^{*i}_j = R^i_j = a^2F^2h^i_j = F^{*2}h^{*i}_j$.

This shows that the Randers metric F^* is of constant curvature 1.

This Randers metric is positive definite also. Thus we can state

Theorem 4. *Let $(M, F = \alpha + \beta)$ be the Randers space induced by a connected α -Sasakian generalized Sasakian space form $M(f_1, f_2, f_3)$, where $\alpha = \sqrt{a_{ij}(x)y^iy^j}$, $\beta = \eta_i(x)y^i$. If $f_2 = f_3 = -c^2a^2$ then the Randers space $(M, F^* = aF)$ is a Randers space of curvature 1.*

In an b -Kenmotsu manifold, we have

$$\begin{aligned}
 (28) \quad & \eta_{i|j} = b(a_{ij} - \eta_i \eta_j), \\
 (29) \quad & \eta_{i|j} + \eta_{j|i} = b(a_{ij} - \eta_i \eta_j), \\
 (30) \quad & \eta_{i|j} - \eta_{j|i} = 0, \\
 (31) \quad & \eta_{i|j} \xi^i = \eta_{i|j} \xi^j = 0, \\
 (32) \quad & \xi^i (\eta_{i|j} - \eta_{j|i}) = 0.
 \end{aligned}$$

Suppose the Randers metric $F = \alpha + \beta$, where $\alpha = \sqrt{a_{ij}(x)y^i y^j}$, $\beta = \eta_i(x)y^i$ is induced by a b -Kenmotsu manifold. Then F is a Randers metric on M which is not positive definite. For a Randers metric $F = \alpha + \beta$ induced by a b -Kenmotsu manifold, we have $b_i = \eta_i$, and so $s_{ij} = \frac{1}{2}(b_{i|j} - b_{j|i}) = 0$, $s_i = b^j s_{ij} = 0$, $r_{ij} = b(a_{ij} - b_i b_j)$ and $e_{00} = 2c(a_{ij} - b_i b_j)$, where $c = \frac{b}{2}$.

Hence the spray coefficients G^i and the Riemann tensor R^i_j of F are given by

$$\begin{aligned}
 (33) \quad & G^i = G^i \alpha + \frac{\chi}{2F} \\
 (34) \quad & R^i_k = \alpha R^i_k + 3\left(\frac{\chi^2}{4F^2} - \frac{\Psi}{2F}\right) \left(\delta_k^i - \frac{F_{y^k}}{F} y^i\right) + \tau_k y^i,
 \end{aligned}$$

where $\chi = b_{i|j} y^i y^j$, $\Psi = b_{i|j|k} y^i y^j y^k$, $\tau_k = \frac{1}{F}(b_{i|j|k} - b_{i|k|j}) y^i y^j = -\frac{1}{F} b_j \alpha R^j_k$.

Suppose F has constant Ricci curvature λ and α has constant curvature μ . Then

$$\begin{aligned}
 Ric &= (n - 1)\lambda F^2, \\
 (35) \quad & \alpha R^i_k = \mu \alpha^2 \left(\delta_k^i - \frac{\alpha_{y^k}}{\alpha} y^i\right), \alpha Ric = (n - 1)\mu \alpha^2.
 \end{aligned}$$

From (34), we obtain

$$(36) \quad Ric = \alpha Ric + 3(n - 1) \left(\left(\frac{\chi}{2F}\right)^2 - \frac{\Psi}{2F}\right)$$

and $R^i_k = \lambda F^2 \delta_k^i + \tilde{\tau}_k y^i$, where $\tilde{\tau}_k y^k = -\lambda F^2$.

i.e. F has constant curvature λ .

From (36), it follows that F has constant Ricci curvature λ if and only if

$$(37) \quad \mu \alpha^2 + 3 \left(\left(\frac{\chi}{2F}\right)^2 - \frac{\Psi}{2F}\right) = \lambda F^2.$$

The above equation is equivalent to following two equations:

$$(38) \quad 3\chi^2 = 2\beta\Psi + 4(\lambda - \mu)\alpha^4 + 4(6\lambda - \mu)\alpha^2\beta^2 + 4\lambda\beta^2.$$

$$(39) \quad \Psi = 4(\mu - 2\lambda)\alpha^2\beta - 8\lambda\beta^3.$$

The equation (39) in (38) gives

$$(40) \quad 3\chi^2 = 4(\lambda - \mu)\alpha^4 + 4(2\lambda + \mu)\alpha^2\beta^2 - 12\lambda\beta^4.$$

Differentiating covariantly and transvecting the resulting by y^k , we obtain

$$(41) \quad 3\Psi = 4(\mu + 2\lambda)\alpha^2\beta - 24\lambda\beta^3.$$

From (39) and (41), we obtain $\mu = 4\lambda$. Putting this in (40), we obtain $\chi^2 = -4\lambda(\alpha^2 - \beta^2)$.

This shows that λ is negative. Thus we have

Theorem 5. *Let $(M, F = \alpha + \beta)$ be the Randers space induced by an b -Kenmotsu manifold, where $\alpha = \sqrt{a_{ij}(x)y^i y^j}$, $\beta = \eta_i(x)y^i$. If F has constant Ricci curvature λ and α has constant curvature μ , then $\lambda = \frac{1}{4}\mu$ and this λ is negative.*

We next see when α has constant curvature. We have,

- (1) the ϕ -sectional curvature of a generalized Sasakian space form $M(f_1, f_2, f_3)$ is $f_1 + 3f_2$ [P. Alegre and A. Carriazo, 2008].
- (2) a Kenmotsu manifold of constant ϕ -sectional curvature is a Riemannian space form of constant sectional curvature -1 [Kenmotsu 1972].

Thus if f_1 and f_2 are constants, then b -Kenmotsu generalized Sasakian space form is a Riemannian space form of constant sectional curvature -1 . i.e. α has constant curvature -1 . From the above discussions, we have

Theorem 6. *Let $(M, F = \alpha + \beta)$ be the Randers space induced by an b -Kenmotsu generalized Sasakian space form with f_1, f_2 as constants. If F has constant Ricci curvature λ , then α has constant curvature -1 and F has constant curvature $\lambda = -\frac{1}{4}$.*

Let $F = \alpha + \beta$ be a Randers metric induced by b -Kenmotsu manifold.

Since $b_i = \eta_i$, from (29) and (30), we have

$s_{ij} = \frac{1}{2}(b_{i|j} - b_{j|i}) = 0$ and $e_{00} = 2c(a_{ij} - b_i b_j)$, where $c = \frac{b}{2}$. We have the following theorem due to [Zhongmin Shen, 2003]:

Theorem 7. *Let $F = \alpha + \beta$ be a Randers metric of constant curvature $K = \lambda$ on a manifold M . Suppose that F satisfies $e_{00} = 2c(\alpha^2 - \beta^2)$ for*

some scalar function $c(x)$ on M and β is closed. Then $\lambda = -c^2 \leq 0$. F is either locally Minkowskian $\lambda = 0$ or curvature in the form $\lambda = -c^2$.

Thus it follows that if $b = 0$, then $\lambda = 0$ and the Randers space (M, F) reduces to a locally Minkowskian space.

If $b \neq 0$, then the Randers space (M, F) is of constant negative curvature $\lambda = -\frac{b^2}{4}$. Thus we state that

Theorem 8. *If M is an b -Kenmotsu generalized Sasakian space form with f_1 and f_2 are constants and if the induced Randers metric $F = \alpha + \beta$ has constant Ricci curvature, then b must be equal to one.*

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