

"Vasile Alecsandri" University of Bacău
Faculty of Sciences
Scientific Studies and Research
Series Mathematics and Informatics
Vol. 26(2016), No. 1, 47-54

SOME GEOMETRICAL PROPERTIES OF PFAFF SYSTEMS ON MANIFOLDS

VALER NIMINET

Abstract. We continue our investigation [7] of Pfaff systems on manifolds by studying some geometrical properties and some consequences of these structures. We point out new geometrical invariants of a distributions on manifolds.

1. INTRODUCTION

As we previously shown in [7], if X is C^∞ manifold of dimension $n + m$ a distribution on X is a mapping $x \rightarrow H_x \subset T_x X$, $x \in X$ with the properties: H_x is a linear subspace of dimension n in $T_x X$ and for every $x_0 \in X$, there exists an open neighborhood U and the vector fields X_1, \dots, X_n on U which are linearly independent on U and $H_x = \text{span}[X_1(x), \dots, X_n(x)]$, $\forall x \in U$. Also, we shown in [7] that a Pfaff system is a mapping $\epsilon : x \rightarrow \epsilon_x \subset T_x^* X$, $x \in X$, with the properties ϵ_x is a linear subspace of dimension m and for any $x_0 \in X$, there exists an open neighborhood U and the 1-forms $\omega^1, \dots, \omega^m$ on U which are linear independent and

Keywords and phrases: Pfaff systems, distributions, structure equations

(2010) Mathematics Subject Classification: 53C99.

$\epsilon_{x_0} = \text{span}[\omega^1(x_0), \dots, \omega^m(x_0)].$

Let 1-forms (ω^a) with :

$$(1.1) \quad \omega^a(x) = \omega_\alpha^a(x) dx^\alpha, \text{rank}(\omega_\alpha^a) = m,$$

with a sum over $\alpha = 1, 2, \dots, d = \dim X$ and $a = 1, 2, \dots, m$ according to the Einstein convention on summation.

Assume that the first m lines in the matrix $(\omega^a \alpha)$ are linear independent and denote by (ϕ_c^b) the inverse of the matrix (ω_b^a) from the expression $(\omega^a \alpha) = (\omega_b^a, \pi \alpha_i)$.

Then, $(\phi_c^a)(\omega_b^c, \pi_i^c) = (\delta_b^a, N_i^a)$.

The lines of this last matrix define the 1-forms

$$(1.2) \quad \tilde{\omega}^a = dx^a + N_i^a(x) dx^i,$$

that satisfy $\tilde{\omega}^a = \phi_c^a \omega^c$.

Thus $(\tilde{\omega}^a)$ span the same Pfaff system as (ω^a) .

In [7] we shown that the 1- forms (ω^a) may be replaced with the 1-forms $\delta y^a = dy^a + N_i^a(x, y) dx^i$ when the coordinates (x^α) on X are separated in (x^i, x^a) and (x^a) are denoted as (y^a) and we compute $d(\delta y^a)$ and put the result into the form

$$(1.3) \quad d(\delta y^a) + \omega_b^a \wedge \delta y^b = \Omega^a$$

that provides a first structure equation and introduces the 2- forms of torsion Ω^a .

Exterior differentiating again we get the first Bianchi identity

$$(1.4) \quad d\Omega^a + \omega_b^a \wedge \Omega^b = \theta_c^a \wedge \delta y^c,$$

where the equality

$$(1.5) \quad \theta_c^a = d\omega_c^a + \omega_b^a \wedge \omega_c^b$$

represents a second structure equation.

A new exterior differentiation leads to the second Bianchi identity:

$$(1.6) \quad d\theta_b^a + \omega_c^a \wedge \theta_b^c = \theta_c^a \wedge \omega_b^c.$$

2. MAIN RESULT

We know that the structure equations (1.3) and (1.5) introduce the 2-forms of torsion Ω^a and the 2-forms of curvature θ_b^a . We notice that for certain particular distributions that are used in Lagrange geometry [4] as well as in the general setting from [6] the 2-forms Ω^a

$$(2.1) \quad \Omega_{ij}^a = \delta_i N_j^a - \delta_j N_i^a,$$

are called the curvature of the distribution H .

The 2-forms of curvature θ_b^a do not belong to the ideal δy^a if and only if $\frac{\partial^2 N_i^a}{\partial y^b \partial y^c} = 0$, that is if and only if

$$(2.2) \quad N_i^a(x, y) = \Gamma_{ci}^a(x) y^c + K_i^a(x).$$

It follows

$$(2.3) \quad \begin{aligned} \omega_b^a &= \Gamma_{bi}^a(x) dx^i, \\ \theta_b^a &= \frac{1}{2} \left(\frac{\partial \Gamma_{bj}^a}{\partial x^i} - \frac{\partial \Gamma_{bi}^a}{\partial x^j} + \Gamma_{ci}^a \Gamma_{bj}^c - \Gamma_{cj}^a \Gamma_{bi}^c \right) dx^i \wedge dx^j := \frac{1}{2} R_{b \ i j}^a dx^i \wedge dx^j \\ \Omega^a &= \frac{1}{2} \left(R_{b \ i j}^a y^b + \frac{\partial K_i^a}{\partial x^j} + K_j^c \Gamma_{ci}^a - K_i^c \Gamma_{cj}^a \right) dx^i \wedge dx^j. \end{aligned}$$

where (θ_b^a) deserve the name of curvature 2-forms.

For $K_i^a = 0$, the coefficients of ω^a reduce to $R_{bij}^a y^b$ one of the torsions of the Cartan connection in a Finsler space.

If we keep the splitting of coordinates on X in the form (x^i, y^a) , a change $(x^i, y^a) \rightarrow (\tilde{x}^i, \tilde{y}^a)$ of these coordinates has the form

$$(2.4) \quad \begin{aligned} \tilde{x}^i &= \tilde{x}^i(x^i, y^a) \\ \tilde{y}^a &= \tilde{y}^a(x^i, y^b), \end{aligned}$$

with

$$(2.5) \quad \frac{\partial(\tilde{x}^i, \tilde{y}^a)}{\partial(x^i, y^a)} \neq 0.$$

We obtain:

$$(2.6) \quad \begin{aligned} d\tilde{x}^i &= \frac{\delta \tilde{x}^i}{\delta x^j} dx^j + \frac{\partial \tilde{x}^i}{\partial y^a} \delta y^a = A_j^i dx^j + A_a^i \delta y^a, \\ d\tilde{y}^a &= \frac{\delta \tilde{y}^a}{\delta x^j} dx^j + \frac{\partial \tilde{y}^a}{\partial y^b} \delta y^b = A_j^a dx^j + A_b^a \delta y^b, \end{aligned}$$

where $A_j^i = \frac{\delta \tilde{x}^i}{\delta x^j}$, $A_a^i = \frac{\partial \tilde{x}^i}{\partial y^a}$

The mapping given by (2.4) may be viewed as a local diffeomorphism $\phi : X \rightarrow X$. This induces an isomorphism $\phi_* : TX \rightarrow TX$ which has to satisfy

$$(2.7) \quad \phi_*(H) = H,$$

for any distribution H on X .

Let H be spanned by $\delta_i = \frac{\partial}{\partial x^i} - N_i^a(x, y) \frac{\partial}{\partial y^a}$

and let $\tilde{\delta}_i = \frac{\partial}{\partial \tilde{x}^i} - \tilde{N}_i^a(\tilde{x}, \tilde{y}) \frac{\partial}{\partial \tilde{y}^a}$ be the local vector fields which span H when it is regarded with respect to the coordinates (\tilde{x}, \tilde{y}) .

We know that the condition (2.7) is equivalent to the equalities $\phi_*(\delta_i) = \lambda_i^j \tilde{\delta}_j$, $i = 1, 2, \dots, n$ for a matrix (λ_i^j) with $\tilde{\delta}(\lambda_i^j) \neq 0$.

We compute $\phi_*(\delta_i) = A_i^j \frac{\partial}{\partial \tilde{x}^j} + A_i^a \frac{\partial}{\partial \tilde{y}^a} = A_i^j \tilde{\delta}_j + (A_i^a + A_i^j \tilde{N}_j^a) \frac{\partial}{\partial \tilde{y}^a}$.

It comes out that (2.7) holds if and only if the following two conditions are satisfied:

$$(2.8) \quad \tilde{\delta}(A_i^j) \neq 0,$$

$$(2.9) \quad A_i^a + A_i^j \tilde{N}_j^a = 0.$$

Assume for a moment that (2.8) holds. Then the functions \tilde{N}_j^a are completely determined from (2.9) in the form $\tilde{N}_j^a = (A^{-1})_j^i A_i^a$.

Using again (2.9) we get

$$\delta \tilde{y}^a = (A_b^a + \tilde{N}_i^a A_b^i) \delta y^b := B_b^a \delta y^b$$

and we must have

$$\tilde{\delta}(B_b^a) \neq 0.$$

Denoting the inverse of the matrix $A_j^i = (\frac{\partial \tilde{x}^i}{\partial x^j})$ by $(\frac{\delta x^i}{\delta x^j})$, the condition (2.9) takes the form

$$(2.10) \quad \tilde{N}_j^a = \frac{\delta x^i}{\delta \tilde{x}^j} N_i^b \frac{\partial \tilde{y}^a}{\partial y^b} - \frac{\delta x^i}{\delta \tilde{x}^j} \frac{\partial \tilde{y}^a}{\partial x^i}.$$

The equation (2.10) simplifies if $(\frac{\partial \tilde{x}^j}{\partial y^a}) = (0)$, that is in (2.4) we have $\tilde{x}^i = \tilde{x}^i(x^j)$. In this case $A_j^i = \frac{\partial \tilde{x}^i}{\partial x^j}$ and (2.10) reduces to

$$(2.11) \quad \tilde{N}_j^a = \frac{\partial x^i}{\partial \tilde{x}^j} N_i^b \frac{\partial \tilde{y}^a}{\partial y^b} - \frac{\partial x^i}{\partial \tilde{x}^j} \frac{\partial \tilde{y}^a}{\partial x^i}.$$

which is the law of transformation of the coefficients of a nonlinear connection in a vector bundle, [4].

Now we search for the behavior of ω_{ij}^a under the local diffeomorphism ϕ . We have seen that $\delta \tilde{y}^a - B_b^a \delta y^b = 0$.

We exterior differentiate this equality and use in the result the followings:

$$(2.12) \quad \begin{aligned} d(\delta y^a) &= \frac{1}{2} \Omega_{ij}^a dx^i \wedge dx^j - \omega_{bi}^a dx^i \wedge \delta y^b, \omega_{bi}^a = \frac{\partial N_i^a}{\partial y^b} \\ d(\delta \tilde{y}^a) &= \frac{1}{2} \tilde{\Omega}_{ij}^a d\tilde{x}^i \wedge d\tilde{x}^j - \tilde{\omega}_{bi}^a d\tilde{x}^i \wedge \delta \tilde{y}^b, \end{aligned}$$

as well as (2.6).

The coefficients of the exterior products $dx^i \wedge dx^j$, $\delta y^b \wedge dx^k$, $\delta y^c \wedge \delta y^b$ have to be zero.

Therefore, we have

$$(2.12') \quad \tilde{\omega}_{kh}^a A_i^k A_j^h = B_b^a \omega_{ij}^b,$$

$$\tilde{\omega}_{ci}^a B_b^c A_k^i + \frac{1}{2} \tilde{\omega}_{ij}^a (A_b^i A_k^j - A_k^i A_b^j) = B_c^a \omega_{bk}^c - \frac{\delta B_b^a}{\delta x^k}$$

$$\frac{1}{2} \tilde{\omega}_{ij}^a (A_c^i A_d^j - A_d^i A_c^j) - \tilde{\omega}_{bi}^a (A_c^i B_d^b - A_d^i B_c^b) = \tilde{\omega}_{ci}^a A_d^i - \tilde{\omega}_{di}^a A_c^i.$$

For the horizontal vector field $U = U^i \delta_i$ and $V = V^j \delta_j$, we have $[U, V] = U^i \delta_i(V^j) \delta_j - V^j \delta_j(U^i) \delta_i - U^i V^j \Omega_{ij}^a \frac{\partial}{\partial y^a}$ and it follows that $[U, V]$ is horizontal if and only if $\Omega_{ij}^a = 0$.

If the distribution H is a subbundle of TX we may consider the quotient vector bundle TX/H as well as the vector bundle $\Lambda^2 H$.

Then $\delta_i \wedge \delta_j$ is a basis of local sections in $\Lambda^2 H$.

In [5] one says that the curvature of the distribution H is the vector bundle morphism $F : \Lambda^2 H \rightarrow TX/H$ given by $F(U \wedge V) = -[U, V] \bmod H$ for every sections U, V in H (horizontal vector fields).

The mapping F is indeed a tensorial one since $[fU, gV] \bmod H = fg[U, V] \bmod H$. We have:

$$F(U, V) = -[U, V] \bmod H = U^i V^j [\delta_i, \delta_j].$$

Hence F is completely determined by Ω_{ij}^a and it vanishes if and only if $\Omega_{ij}^a = 0$.

In order to study the behavior of θ by the local diffeomorphism ϕ we shall use a matrix notation. We write $\delta y = (\delta y^a)$ as a column matrix and rewrite (1.1) - (1.3) as follows:

$$d(\delta y) + \omega \wedge \delta y = \omega,$$

$$d\Omega + \omega \wedge \omega = \theta \wedge \delta y,$$

$$\theta = d\omega + \omega \wedge \omega,$$

$$(2.13) \quad d\theta + \omega \wedge \theta = \theta \wedge \omega.$$

By ϕ we get $\delta \tilde{y} = B \delta y$.

We exterior differentiate this equality as well as $d(\delta \tilde{y}) + \tilde{\omega} \wedge \delta \tilde{y} = \tilde{\Omega}$.

After some calculation we get

$$(2.14) \quad (B\Omega - dB - \tilde{\Omega}B) \wedge \delta y = B\Omega - \tilde{\Omega}.$$

Let J be a matrix of 1-forms such that $J \wedge \delta y$ to represent the component of $\tilde{\Omega}$ from the ideal $\{\delta y\}$.

We add $J \wedge \delta y$ to the both side of (2.14). It results

$$(2.15) \quad (B\Omega - dB - \tilde{\Omega}B + J) \wedge \delta y = B\Omega - (\tilde{\Omega} - J \wedge \delta y).$$

In (2.15), the left side is in ideal $\{\delta y\}$ and the right side is not in this ideal. The equality holds only if the both sides vanish. Thus we obtain

$$(2.16) \quad \tilde{\omega}B = B\omega - dB + J, \quad \tilde{\Omega} = B\Omega + J \wedge \delta y.$$

We know:

$$\tilde{\theta} = d\tilde{\omega} + \tilde{\omega} \wedge \tilde{\omega}$$

Then

$$\begin{aligned} \tilde{\theta}B &= d\tilde{\omega}B + \tilde{\omega} \wedge \tilde{\omega}B = d(\tilde{\omega}B) + \tilde{\omega} \wedge dB + \omega \wedge \tilde{\omega}B = \\ &= d(\tilde{\omega}B) + \tilde{\omega} \wedge (dB + \tilde{\omega}B) = d(\tilde{\omega}B) + \tilde{\omega} \wedge (B\omega + J) = \\ &= dB \wedge \omega + Bd\omega + dJ + \tilde{\omega} \wedge J + \tilde{\omega}BB^{-1} \wedge B\tilde{\omega} = \\ &= B(d\omega + \omega \wedge \omega) + dJ + J \wedge \omega + \tilde{\omega} \wedge J = B\theta + dJ + J \wedge \omega + \tilde{\omega} \wedge J, \end{aligned}$$

where we have also used

$$d(\tilde{\omega}B) = d\tilde{\omega}B + \tilde{\omega} \wedge dB$$

So, the connection between $\tilde{\theta}$ and θ is:

$$\tilde{\theta}B = B\theta + dJ + J \wedge \omega + \tilde{\omega} \wedge J.$$

REFERENCES

- [1] M.Anastasiei, **Generalized affine connections in Banach vector bundles**, An. Științ. Univ. "Al. I. Cuza" Iași Sect. I a Mat. (N.S.) 26 (1980), no. 2, 381–388.
- [2] O. Lungu, V.Niminet, **General Randers mechanical systems**, Scientific Studies and Research, Vol 22, Nr.1, 2012, 25-30.
- [3] O. Lungu, V.Niminet, **Some properties of a R-Randers quartic**, Scientific Studies and Research, Vol 20, Nr.1, 2010, 133-140.
- [4] R.Miron, M. Anastasiei, **The geometry of Lagrange spaces: theory and applications**, Fundamental Theories of Physics 59, Kluwer Academic Publishers, 1994.

- [5] R. Miron, V.Niminet, **The Lagrangian Geometrical model and The associated dynamical system of a nonholonomic mechanical system**, Facta universitatis-series Mechanics Automatic Control and Robotics, Vol 5, No.1, 1-24.
- [6] R. Montgomery, **A tour of subriemannian geometries, their geodesics and applications**, Mathematical Survey and Monographs, vol. 91, AMS, 2002.
- [7] V. Niminet, **Pfaff systems on manifolds**, Stud.Cercet. Ştiinţ. Ser. Mat. Univ. Bacău, No. 14(2004),91-94.
- [8] V. Niminet, **Generalized Lagrange spaces of a relativistic optics**, Tensor, New Series, 66(2), 180-184.
- [9] V. Niminet, **Structure equations for distributions on manifolds**, Analele Univ.Al.I.Cuza, Seria Matematica, Tomul LIV, Fasc.1,2008, 51-64.
- [10] V. Niminet, **New geometrical properties generalized Lagrange spaces of relativistic optics**, Tensor, New Series, 68(1), 66-70.

Department of Mathematics, Informatics and Education Sciences,
 Faculty of Sciences,
 "Vasile Alecsandri" University of Bacau ,
 157 Calea Marasesti, 600115 Bacau , ROMANIA
 E-mail address: valern@ub.ro